

ML000007

Next Assembly	Used On	Revisions		Rev Y	
		Ltr	Description		
First Application		A	Revised per ECN TRN 6212, DRC E9404 dated 2/21/87	3/16/87	S. Gregg
		B	Revised per ECN TRN 6366/DRC #F2117, dated 9/3/87	10/1/87	S. Gregg
		C	Revised per ECN TRN 6700, DRC F5003.	4/1/89	S. Gregg
		D	Revised per ECN TRN 6760/DRC #F6668.	8/10/89	S. Gregg
		E	Revised per ECN TRN 6913/DRC #F9629.	4/17/89	S. Gregg
		F	Revised per ECN TRN 7064, DRC G4672.	12/18/89	S. Gregg
		G	Revised per ECN TRN 7181, DRC G6579.	5/6/90	S. Gregg
		H	Revised per ECN TRN 7427, DRC H0603.	10/23/90	S. Gregg
		J	Revised per ECN TRN 7550.	3/11/91	S. Gregg
		K	Revised per ECN TRN 7782.	6/10/91	S. Gregg
		L	Revised per ECN TRN 8072.	3/16/92	S. Gregg
		M	Revised per ECN TRN 8459.	CM/Wong 3/22/93	S. Gregg
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		P	Revised per ECN TRP 0992.	4/23/93	S. Gregg
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CURRENT DESIGN ACTIVITY CAGE CODE 06887 LOCKHEED MARTIN SPACE SYSTEMS COMPANY MISSILES & SPACE OPERATIONS SUNNYVALE, CA 94088-3504					

Revision Record Continued on Sheet - 2

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	Approved <i>R.M. Cummings</i> Date <i>September 8, 1996</i>				
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<i>R.M. Cummings 9-15-96 Product Assurance</i>		A	49671	IS-2624483	
				Sheet 1 of 120	

ITAR CONTROLLED DATA

Size
A

Code Ident No.
06887

IS-2624483

Sheet 2

TIROS
UNIQUE INTERFACE SPECIFICATION
For The
ADVANCED MICROWAVE
SOUNDING UNIT-A2 (AMSU-A2)

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ITAR CONTROLLED DATA

Size A	Code Ident No. 49671	IS-2624483
		Sheet 3

TABLE OF CONTENTS

Section	Page
1.0 SCOPE	10
2.0 APPLICABLE DOCUMENTS	11
2.1 Reference Documents	11
2.1.1 Spacecraft Contractor Originated Documents	11
2.1.2 Instrument Contractor Originated Document - Aerojet	12
2.1.3 NASA Originated Documents	12
3.0 REQUIREMENTS	13
3.1 Electrical	13
3.1.1 Grounds	13
3.1.1.1 Exceptions	13
3.1.1.2 Other Grounding Requirements	13
3.1.2 Connectors	14
3.1.2.1 Exceptions	14
3.1.2.2 Connector Allocation	15
3.1.2.3 Connector Mounting Hardware	15
3.1.2.4 Connector Keying Requirements	15
3.1.2.5 Harness Mating Connectors	15
3.1.2.6 Pin Designations	15
3.1.2.7 Intra-Instrument Harness Requirements	15
3.1.2.8 Connector Location and Access	15
3.1.3 Power	24
3.1.3.1 Power Sources	24
3.1.3.2 +28-Volt Main Bus Power Requirements	24
3.1.3.3 +28-Volt Analog Telemetry Bus Power Requirements	34
3.1.3.4 +28-Volt Pulse Load Bus Power Requirements	35
3.1.3.5 +10.0-Volt Interface Bus Power Requirements	40
3.1.3.6 Power Exceptions	43
3.1.4 Input Timing and Control Signals	44
3.1.4.1 Clocks	44
3.1.4.2 Synchronization Signals	44
3.1.4.3 Commands	48
3.1.4.4 Exceptions	52
3.1.5 Instrument Output Signals	52
3.1.5.1 General	52
3.1.5.2 Digital A Data	52
3.1.5.3 Digital B Telemetry	62
3.1.5.4 Analog Telemetry	64
3.1.5.5 Exceptions	64
3.1.6 Test Points	66
3.1.6.1 Input Test Points	66
3.1.6.2 Output Test Points	66
3.2 Mechanical Interface	68
3.2.1 Physical Characteristics	68
3.2.1.1 Dimensions	68

ITAR CONTROLLED DATA

Size	Code Ident No.		
A	06887	IS-2624483	
Sheet 4			

TABLE OF CONTENTS (Continued)

Section		Page
3.2.1.2 Weight		68
3.2.1.3 Moments of Inertia		68
3.2.1.4 Disturbance Torque		71
3.2.1.5 Center of Gravity		71
3.2.2 Instrument Mounting		73
3.2.2.1 Instrument Mounting Surface		73
3.2.2.2 Mounting Hole Position		73
3.2.2.3 Instrument Location		73
3.2.2.4 Spacecraft Mounting Surface		73
3.2.3 Mechanisms		74
3.2.4 Fields-of-View		74
3.2.4.1 Instrument Requirements		74
3.2.4.2 Spacecraft Provisions		77
3.2.5 Alignment		77
3.2.5.1 Reference Surfaces		78
3.2.6 Protective Covers		83
3.2.6.1 Accessibility		83
3.2.6.2 Installation Requirements		83
3.2.6.3 Removal Requirements and Reasons		83
3.2.6.4 Precautions		83
3.2.7 Instrument Materials and Finishes		84
3.2.8 Spacecraft Harness Clamp Requirements		84
3.2.9 Marking		84
3.3 Thermal Interface		85
3.3.1 Responsibility		85
3.3.1.1 Instrument Vendor		85
3.3.1.2 Spacecraft Contractor		85
3.3.2 General Requirements		86
3.3.3 Instrument Temperature Requirements		86
3.3.4 Spacecraft (ESM) Temperature Specifications		86
3.3.4.1 Operational Conditions		86
3.3.4.2 Survival (Safestate) Condition		86
3.3.5 Instrument Thermal Control Components		89
3.3.5.1 Passive Control Elements		89
3.3.5.2 Active Control Elements		89
3.4 Environmental Interface		90
3.4.1 Magnetic Characteristics		90
3.4.2 EMI		90
3.4.3 Flight Environment		91
3.5 Operational Requirements and Precautions		91
3.5.1 Storage Requirements		91
3.5.2 Test Requirements		91
3.5.3 Operational Requirements		92
3.5.3.1 Command Sequences		92
3.5.3.2 Test Turn-On Constraints		93
3.5.3.3 Initial In Orbit Turn-On Constraints		93
3.5.3.4 AIP Switchover		94
3.5.3.5 Launch Configuration		94

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 5

TABLE OF CONTENTS (Continued)

Section	Page
4.0 INSTRUMENT INTEGRATION, TEST AND OPERATING REQUIREMENTS AND CONSTRAINTS	95
4.1 Test Equipment and Service	95
4.1.1 Equipment to be Supplied by Instrument Contractor to the Spacecraft Contractor	95
4.1.1.1 Special Test Equipment (STE)	96
4.1.1.2 Calibration Test Equipment (CTE)	96
4.1.1.3 Contamination Cover	96
4.1.1.4 Handling Fixture	96
4.1.1.5 Thermal Blankets	96
4.1.1.6 Optical Alignment Equipment	96
4.1.1.7 Lifting Fixture	97
4.1.2 Services Provided by Instrument Contractor at the Spacecraft Contractor	98
4.1.2.1 Bench Test	98
4.1.2.2 Data Analysis	98
4.1.2.3 Troubleshooting	98
4.1.2.4 Warranty	98
4.1.2.5 Equipment Maintenance to be Supplied by Instrument Contractor	99
4.1.3 Software to be Supplied by the Instrument Contractor to the Spacecraft Contractor	99
4.1.3.1 Bench Test Procedure	99
4.1.3.2 GSE Operations Manuals and Procedures	99
4.1.3.3 Data Book, Specification Verification and Calibration	99
4.1.3.4 Handling Procedures	99
4.1.4 Equipment and Services to be Supplied by the Spacecraft Contractor for Direct Instrument Support	99
4.1.4.1 Spacecraft Contractor Supplied Equipment and Services	99
4.1.4.2 Spacecraft Contractor Supplied Labor for Testing at the Instrument Level	101
4.1.5 Test Access to the AMSU-A2	101
4.1.5.1 During Bench Checkout	101
4.1.5.2 During Satellite Level Tests	101
4.1.5.3 Access for Inspecting Scan Antennae, Reflectors, and Thermal Mirrors	101
4.1.5.4 During Launch Pad Testing (Shroud On)	101
4.2 Acceptance Test Performed at the Instrument Vendors	102
4.3 Testing at the Spacecraft Contractor's Facility	102
4.3.1 Instrument Evaluation Tests	102
4.3.1.1 Receiving	102
4.3.1.3 Degaussing	103
4.3.1.4 Incoming Inspection - Electrical (Bench Test)	103
4.3.1.5 Storage and Storage Testing	103
4.3.1.6 Instrument Test Matrix	103
4.3.3 System Evaluation Test	110
4.3.3.1 Initial Power and Functional Checks (IPF)	110
4.3.3.2 Detail Electrical Test (DET)	111
4.3.3.3 Spacecraft Electrical Performance Evaluation Test (SEPET)	112
4.3.4 Satellite Environment Test	113
4.3.4.1 Aliveness Test	113
4.3.4.2 Thermal-Vacuum Tests	113
4.3.4.3 Optical Alignment	114
4.3.4.4 Sine Vibration in X, Y, and Z Axes	114
4.3.4.5 Acoustic Vibration	114

ITAR CONTROLLED DATA

Size	Code Ident No.	
A	06887	IS-2624483
		Sheet 6

TABLE OF CONTENTS (Continued)

Section		Page
4.3.4.6 Post-Vibration Deployment Test		114
4.3.4.7 Final Electrical Check		115
5.0 NOTES		114
5.1 Waivers		115
APPENDIX A		117
APPENDIX B		120

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 7

LIST OF ILLUSTRATIONS

Figure		Page
1a.1	+28 Volt Main Bus Peak Power Worst Case Profile for S/N 101-104	27
1a.2	+28 Volt Main Bus Peak Power Worst Case Profile for S/N 105-109	28
1b.1	+28 Volt Main Bus Peak Power Worst Case Profile for S/N 101-104	29
1b.2	+28 Volt Main Bus Peak Power Worst Case Profile for S/N 105-109	30
2	Typical Load Current Ripple	31
3	Worst Case Transient Load	32
4	Typical Load Current Transients	33
5a	+28-Volt Pulse Load Bus Peak Power Worst-Case Profile	36
5b	+28-Volt Pulse Load Bus Peak Power Worst-Case Profile	37
6	+28-Volt Pulse Load Bus Typical Load Current Waveforms	38
7	Typical Motor Start-Up Current Loads	39
8	Typical 10-Volt Bus Load Current Transients and Ripple	41
9	Schematic Diagram of Digital B Power Supply	42
10A	AIP Digital A Interface	45
10B-1	Digital A Data Format - Full Scan Mode	53
10B-2	Digital A Data Format - Warm Cal Mode	56
10B-3	Digital A Data Format - Cold Cal Mode	57
10B-4	Digital A Data Format - Nadir Mode	58
11	AIP Minor Frame Format	61
12A	AMSU-A2 Outline Drawing	69
12B	AMSU-A2 Mounting Hole Locations	70
12C	AMSU-A2 Torque Profile	72
13A	AMSU-A2 F.O.V. Requirement for Both Dimensions	75
13B	FOV Crosstrack Scan Profile	76
14	Orbit-Average Energy Transfer	87
15A	AMSU-A2 Testing at the Spacecraft Contractor's Facility	104
15B	AMSU-A2 Testing at the Spacecraft Contractor's Facility	105
15C	AMSU-A2 Testing at the Spacecraft Contractor's Facility	106
15D	AMSU-A2 Testing at WTR	107
16	AMSU-A2 Conducted Emissions Limits (S/N105 to 109)	115

ITAR CONTROLLED DATA

Size	Code Ident No.	
A	06887	IS-2624483
		Sheet 8

LIST OF TABLES

Table		Page
1	AMSU-A2 INSTRUMENT CONNECTOR REQUIREMENTS	16
2	SPACECRAFT HARNESS CONNECTOR REQUIREMENTS FOR AMSU-A2	17
3A	CONNECTOR PIN DESIGNATIONS-AMSU-A2	18
3B	CONNECTOR PIN DESIGNATIONS AMSU-A2	19
3C	CONNECTOR PIN DESIGNATIONS-AMSU-A2	20
3D	CONNECTOR PIN DESIGNATIONS-AMSU-A2	21
3E	CONNECTOR PIN DESIGNATIONS-AMSU-A2	22
3F	CONNECTOR PIN DESIGNATIONS-AMSU-A2	23
4	AMSU-A2 POWER REQUIREMENTS	25
5	SPACECRAFT/AMSU-A2 CLOCK INTERFACES	46
6	SPACECRAFT/AMSU-A2 SYNCHRONIZATION SIGNAL INTERFACES.....	47
7	SPACECRAFT/AMSU-A2 COMMAND INTERFACES.....	51
8	AMSU-A2 DATA WORD DESCRIPTION	59
9	DIGITAL "B" TELEMETRY FOR AMSU-A2	63
10	AMSU-A2 ANALOG TELEMETRY	65
11	AMSU-A2 TEST POINTS AND GSE INTERFACE (A2-J7 CONNECTOR)	67
12	PULLOUT STRENGTH AND SHEAR FORCE OF INSERT IN ESM EARTH-FACING PANEL	73
13A	AMSU ON-ORBIT UNCERTAINTIES (WRT ESA).....	79
13B	AMSU INITIAL GROUND COREGISTRATION	80
13C	AMSU ALIGNMENT REQUIREMENTS (WRT ESA).....	81
13D	AMSU IN-ORBIT COREGISTRATION	82
14	INSTRUMENT ALLOWABLE TEMPERATURE RANGES.....	88
15	RF FIELDS AT AMSU-A2 INSTRUMENT	90
16A	AMSU-A2 TEST MATRIX.....	108
16B	AMSU-A2 TEST MATRIX.....	109

ITAR CONTROLLED DATA

Size	Code Ident No.				
A	06887		IS-2624483		
				Sheet 9	

1.0 SCOPE

This document establishes the electrical, mechanical and thermal interfaces between the Advanced Microwave Sounding Unit Module A2 and the Advanced TIROS-N (ATN) Spacecraft and Aerospace Ground Equipment.

This document, in conjunction with IS-3267415, also details all environments which will be seen by the instrument from the time of its arrival at the Spacecraft Contractor's facility through spacecraft launch, including all phases of storage and test. In addition, specific information about unique instrument properties or requirements in associated areas (such as power and handling requirements, test requirements, test equipment, targets, etc.) is contained herein.

General interface requirements, common to all instruments, are given in the General Instrument Interface Specification (IS-3267415). In the event of conflict between this specification and the General Instrument Interface Specification, this specification shall govern. Where the requirements for a particular interface parameter are omitted from this specification, the General Instrument Interface Specification requirement shall apply.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 10

2.0 APPLICABLE DOCUMENTS

The latest issue of the following document is invoked in entirety. In the event of conflict between this unique specification and the referenced general document, this unique specification shall govern.

IS-3267415 ATN-KLM General Instrument Interface Specification (GIIS)

2.1 Reference Documents

The current issues of the following documents relate to the interface. Some of these documents are for reference only; others are required documents. The required documents are indicated by an asterisk. Change to these documents which affect form or function of the spacecraft interface will be submitted to the NASA TIROS Project Office for CCR action.

2.1.1 Spacecraft Contractor Originated Documents

- (1) 3278778 Field of View Drawing*
- (2) 3287774 KLM RSS Thermal Finishes*
- (3) 3287775 KLM ESM Thermal Finishes*
- (4) 3287776 KLM IMP Thermal Finishes*
- (5) 20028674 AMSU-A2 Logic Diagram
- (6) 3278200 ATN Spacecraft Assembly*
- (7) 3278776 ATN ESM Assembly, GFE*
- (8) 3767412 Quality Assurance Program for NOAA-KLM
- (9) 3767411 Reliability Program Plan for NOAA-KLM
- (10) 3278779 ATN Spacecraft Orbital Configuration
- (11) 3284735 AMSU-A2 Installation
- (12) 8574806 (NOAA-L) MLIB Installation
- (13) 8574807 (NOAA-M) MLIB Installation
- (14) 8574808 (NOAA-N) MLIB Installation
- (15) 8574809 (NOAA-N') MLIB Installation

*Required

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 11

2.1.2 Instrument Contractor Originated Document - Aerojet

- 1333965 (1) Thermal Interface Control Drawing*
Report #9176 (2) Reduced Thermal Model*
1333965 (3) Outline/Interface Control Drawing*
(4) Schematics (to first active element)
(5) Calibration Test Equipment Required
AE-26157 (a) STE for AMSU-A1 & A2
Report # 10273 (b) AMSU-A B.B. S/C test targets O & M manual

AE-2615/6 (6) Test Data Reduction and Correlation Requirements unique to each instrument provided with calibration log books

AE-26357 (7) Instrument Calibration Procedure

AE-26438 (8) Instrument Handling and Safety Requirements

AE-26438 (9) AMSU-A Instrument Operation & Maintenance Manual (for S/N 101-104)
Report # 10273
AE-26157

AE-26671 (9a) AMSU-A Instrument Operation & Maintenance Manual (for S/N 105-109)

(10) Test Procedures
AE-26438 (a) Pre-installation Bench Checkout (O & M Manual)
Report # 10273 (b) Spacecraft Thermal-Vacuum Target
AE-26157 (c) Special Test Equipment (STE)

1333071 (11) Drill Template Drawing*

Report #9351 (12) Finite Element Model (NASTRAN)*

AS 8096 (13) Connector Specification

AS 26139 (14) TRIAX Connector Specification

1331368 (15) Ground Strap

2.1.3 NASA Originated Documents

- GSFC-S-480-13 GSFC Specification for the Advanced Microwave Sounding Unit (AMSU) S/N 101-104
GSFS-S-480-80 GSFS Specification for the Advanced Microwave Sounding Unit (AMSU) S/N 105-109
GSFC-S-480-40 Performance Assurance Requirements for the Advanced Microwave Sounding Unit-A S/N 101-104
GSFC-S-480-79 Performance Assurance Requirements for the Advanced Microwave Sounding Unit-A S/N 105-109

*Required

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 12

3.0 REQUIREMENTS

3.1 Electrical

The electrical interfaces shall comply with the General Instrument Interface Specification (IS-3267415).

3.1.1 Grounds

The instrument shall conform to the grounding requirements of Section 3.1.1 of the General Instrument Interface Specification, IS-3267415.

3.1.1.1 Exceptions

The exceptions to the above specification are as follows:

The Triax outer shield is connected at both ends to chassis ground.

3.1.1.2 Other Grounding Requirements

- 1) There will be a ground strap

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 13

3.1.2 Connectors

The instrument shall conform to Section 3.1.2 of the General Instrument Interface Specification, IS-3267415.

3.1.2.1 Exceptions

The exceptions to the above specification are as follows:

- 1) Input connector requirements are as shown in Table 1. All multipin connectors are EMI/RFI filter type as specified in Aerojet Specification AS8096. Equivalent non-filter type connector list is given in Table 1. The connector finish is 6061-T6 aluminum with electroless nickel finish per MIL-C-26074.
- 2) Power input connector (J1) will not have 10% spares so as to accommodate safety heater power connection.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 14

3.1.2.2 Connector Allocation

Connector requirements for the instrument shall be as shown in Table 1.

3.1.2.3 Connector Mounting Hardware

Connectors J1, J2, J4, J5, J6, and J7 shall be mounted by using Cannon, ITT P/N D20418-77 Cress, screw lock female.

3.1.2.4 Connector Keying Requirements

The connector keying shall be done in a manner which guarantees that it will be impossible to improperly connect the instrument cables.

3.1.2.5 Harness Mating Connectors

The mating connector requirements for the spacecraft harness shall be as shown in Table 2.

3.1.2.6 Pin Designations

Connector pin designations and shielding requirements for the spacecraft harness shall be as shown in Table 3.

3.1.2.7 Intra-Instrument Harness Requirements

NONE

3.1.2.8 Connector Location and Access

The interface connectors to the spacecraft harness shall be located on the +Y face of the instrument as shown in AESC drawing #1333965.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 15

TABLE 1. AMSU-A2 INSTRUMENT CONNECTOR REQUIREMENTS

<u>Connector Name Code</u>	<u>Type</u>	<u>Description (Pins, Sex)</u>	<u>Function</u>
J1	TD1B25TP (AS8096-25PT-0)	25 pin male	Power Input
J2	TD1E9HS (AS8096-9SH-0)	9 pin female	AIP/Digital A I/O
J3	*63-47000-001 (AE26139-1)	Triax	1.248 MHz Clock
J4	TD1B25TS (AS8096-25ST-0)	25 pin female	Commands Input
J5	TD1A15TS (AS8096-15ST-0)	15 pin female	Digital B Telemetry
J6	TD1C37TP (AS8096-37PT-0)	37 pin male	Analog Telemetry
J7	TD1C37HS (AS8096-37SH-0)	37 pin female	Test/GSE Interface

(Aerojet Part Number)

*Automatic Connector, Inc.

Connectors P/N that begin with "TD" are filter type Cannon connectors.

Equivalent Non-Filter Type Connector P/N

J1	DBM-25P-NMB-K56
J2	DEM-9S-NMB-K56
J4	DBM-25S-NMB-K56
J5	DAM-15S-NMB-K56
J6	DCM-37P-NMB-K56
J7	DCM-37S-NMB-K56

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 16

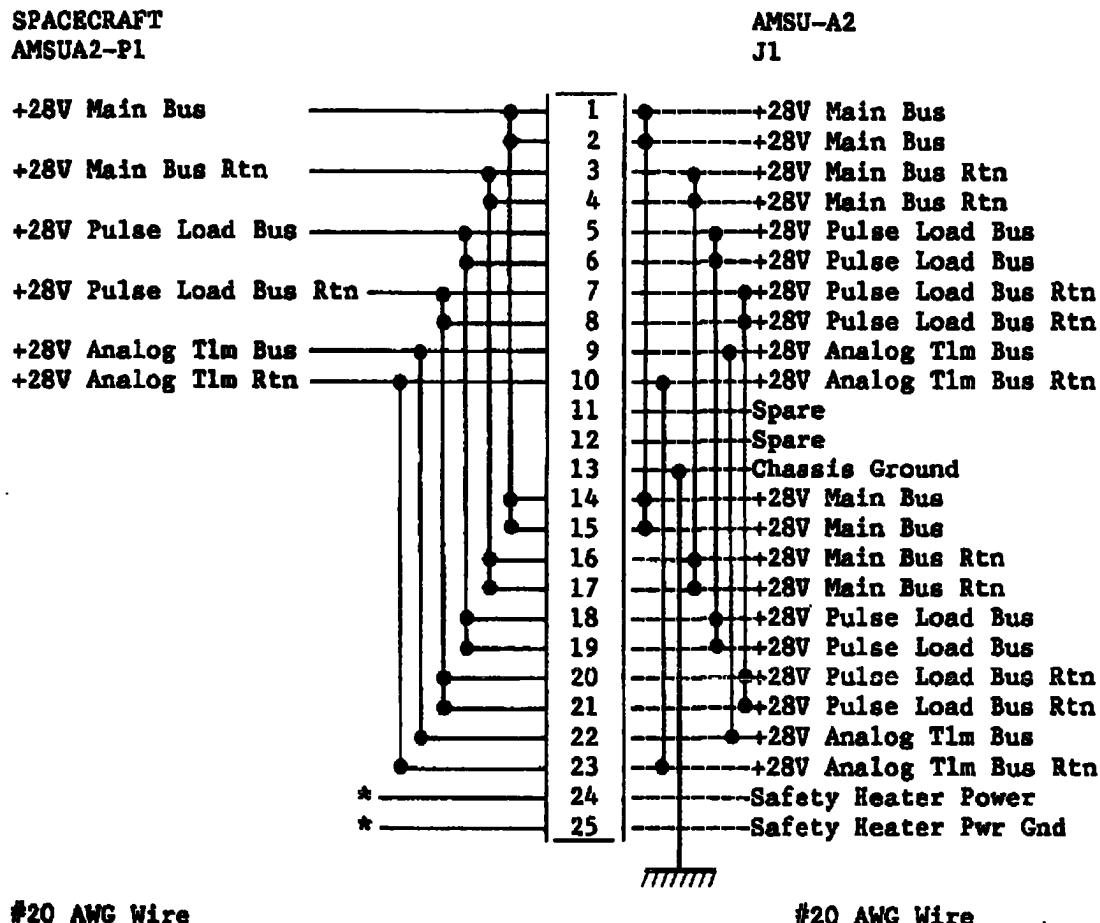
TABLE 2. SPACECRAFT HARNESS CONNECTOR REQUIREMENTS FOR AMSU-A2

<u>S/C Designation</u>	<u>RCA Part No.</u>	<u>Type</u>	<u>Description (Pins, Sex)</u>	<u>Function</u>
P1	1721489-3	DBM-25S-NMB-K56	25 pin female	Power Input
P2	1721490-1	DEM-9P-NMB-K56	9 pin male	AIP/Digital A I/O
P3	2606367-2	RFL6321-90(M1)	Triax	1.248 MHz Clock
P4	1721490-3	DBM-25P-NMB-K56	25 pin male	Commands Input
P5	1721490-2	DAM-15P-NMB-K56	15 pin male	Digital B Telemetry
P6	1721489-4	DCM-37S-NMB-K56	37 pin female	Analog Telemetry

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483	
			Sheet 17

TABLE 3A. CONNECTOR PIN DESIGNATIONS-AMSU-A2



***Pigtails on spacecraft harness for the AMSU-A2 safety heater
(for use in thermal vacuum at the Spacecraft Contractor).**

ITAR CONTROLLED DATA

Size A **Code Ident No.**
06887

IS-2624483

TABLE 3B. CONNECTOR PIN DESIGNATIONS AMSU-A2

Connector: A2-J2 AIP/Digital A I/O

SPACECRAFT
AMSUA2-P2

AMSU-A2	
J2	
1	Chassis Ground
2	Data Clock (C_1)
3	Signal Ground
4	Spare
5	Digital A Data Output
6	Data Enable (A1)
7	8 Sec Sync
8	Spare
9	Spare

ITAR CONTROLLED DATA

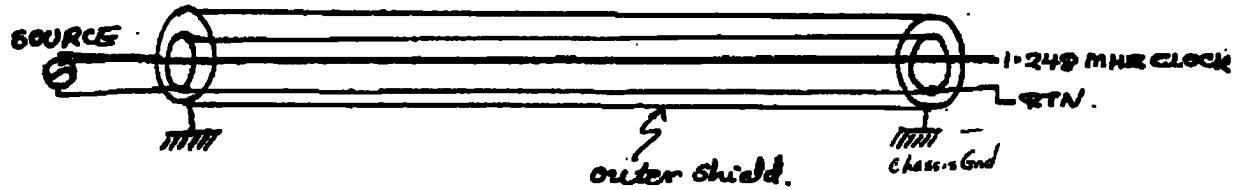
Size A	Code Ident No. 06887	IS-2624483
		Sheet 19

TABLE 3C. CONNECTOR PIN DESIGNATIONS-AMSU-A2

Connector: A2-J3 1.248 MHz Clock

SPACECRAFT
AMSSA2-P3

AMSSA2
J3



ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 20

TABLE 3D. CONNECTOR PIN DESIGNATIONS-AMSU-A2

Connector: A2-J4 Command

SPACECRAFT
AMSU-A2-P4

+10V Int. Bus
+10V Int. Bus Rtn

AMSU-A2	
J4	
1	Chassis Ground
2	Module Power Disconnect
3	Survival Heater ON
4	Module Totally OFF
5	Compensator Motor ON/OFF
6	Antenna at Cold Cal Pos.
7	Spare
8	Antenna at Nadir Pos.
9	Cold Cal Pos. MSB
10	Spare
11	Spare
12	+10V Int. Bus
13	+10V Int. Bus Rtn
14	Module Power Connect
15	Survival Heater OFF
16	Scanner A2 ON/OFF
17	Antenna at Warm Cal Pos.
18	Full Scan
19	Cold Col Pos. LSB
20	Spare
21	Spare
22	Spare
23	Spare
24	+10V Int. Bus
25	+10V Int. Bus Rtn

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 21

TABLE 3E. CONNECTOR PIN DESIGNATIONS-AMSU-A2

Connector: A2-J5 Digital B Telemetry

SPACECRAFT
AMSUA2-P5

AMSU-A2	
J5	
1	Chassis Ground
2	Module Power Disconnect/Connect
3	Cold Cal Pos. MSB
4	Spare
5	Compensator Motor ON/OFF
6	Antenna in Cold Cal Pos. YES/NO
7	Spare
8	Spare
9	Survival Heater ON/OFF
10	Spare
11	Cold Cal Pos. LSB
12	Scanner A2 ON/OFF
13	Antenna in Warm Cal Pos. YES/NO
14	Antenna in Nadir Pos. YES/NO
15	Full Scan Mode YES/NO

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 22

TABLE 3F. CONNECTOR PIN DESIGNATIONS-AMSU-A2

SPACECRAFT
AMSUA2-P6

SPACECRAFT AMSUA2-P6	AMSU-A2 J6
	1 Chassis Ground
	2 RF Shelf A2 Temp
	3 Compensator Motor Temp
	4 Warm Load A2 Temp
	5 Spare
	6 Spare
	7 Spare
No connection on S/C Side	8 A2 Drive Motor Current (Average)
	9 +15 VDC (Antenna Drive)
	10 +5 VDC (Antenna Drive)
	11 +15 VDC (Signal Processing)
	12 +5 VDC (Signal Processing)
	13 L.O. Voltage Ch1 (23.8 GHz)
	14 Spare
	15 Spare
	16 Spare
	17 Spare
	18 Spare
	19 Spare
	20 +28V Analog Tlm Bus Rtn (STE only)*
	21 Spare
	22 A2 Scan Motor Temp
	23 Spare
	24 Spare
	25 Spare
	26 Spare
	27 Compensation Motor Current (Average)
	28 -15 VDC (Antenna Drive)
	29 -15 VDC (Signal Processing)
	30 L.O. Voltage Ch2 (31.4 GHz)
	31 Spare
	32 Spare
	33 Spare
	34 +8 VDC (Receiver) (S/Ns 101-104); +10 VDC (Receiver/Mixer/IF) (S/N 105-109)
	35 Spare
	36 Spare
	37 Spare

* For use at subsystem level testing only; not for instrument level testing. (Open to J1-7, shorted to J1-10).

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 23

3.1.3 Power

3.1.3.1 Power Sources

- (1) The main power required by the AMSU-A2 instrument shall be taken from the +28-Volt Main Bus.
- (2) The +28-Volt Pulse Load Bus shall be used to supply power to the motors and heaters in the AMSU-A2.
- (3) The +28-Volt Analog Telemetry Bus may be used for Telemetry information which is needed when the instrument is not powered and which is not critical to the mission if this bus is lost. (See Para. 3.1.3.3).
- (4) All command and Science Data Interfaces shall be powered from the +10.0-Volt Interface Bus.
- (5) The power drawn from the above sources shall not exceed values in Table 4.

3.1.3.2 +28-Volt Main Bus Power Requirements

3.1.3.2.1 Power Dissipation

The power required by the AMSU-A2 from the +28 Volt Main Bus shall be as shown in Table 4. The peak power worst-case profile on the +28 Volt Main Bus for this instrument shall be as shown in Figure 1.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 24

TABLE 4. AMSU-A2 POWER REQUIREMENTS

+28v Main Bus		+28v Pulse Load Bus		+10V Bus		+28v Analog TM Bus	
Avg. (watts)	Peak* Current (amp)	Avg. (watts)	Peak Current (amp)	Avg. (watts)	Peak Current (amp)	Avg. (watts)	Peak Current (amp)
25.0	1.0	12.0	2.2	0.1	12mA	0.15	0.005

The combined power from Main +28V Bus and +28V Pulse Load Bus shall not exceed 37 watts.

*Steady-state current

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483	
			Sheet 25

3.1.3.2.2 Power Limiting

The instrument shall not limit the short circuit current drain on the spacecraft +28-Volt Main Bus.
The instrument will be serviced by a circuit fused in the spacecraft with a 5 ampere fuse.

3.1.3.2.3 Load Current Ripple

The typical load current ripple on each line, which exceeds the GIIS limit, shall be as shown in Figure 2.

3.1.3.2.4 Transient Loads

- (1) For fuse sizing purposes, the worst-case transient load on each line shall be as depicted in Figure 3.
- (2) See GIIS (IS-3267415) Section 3.1.3.2.6.3. Typical load current transients shall be as shown in Figure 4.
- (3) For S/Ns 101-104, the worst case peak current on the +28V Main Bus occurs during instrument turn-on (See Figure 1a.1) and is 8.3 amps maximum, which exceeds the GIIS spec of \leq 3.0 amps peak.

For S/Ns 105-109, the worst case peak current on the +28V Main Bus occurs during instrument turn-on (See Figure 1a.2) and is 5.7 amps maximum, which exceeds the GIIS spec of \leq 3.0 amps peak.

- (4) For S/Ns 101-104, the rate of rise of the +28V Main Bus transient load current shall be 640 mA/ μ sec maximum, which exceeds the GIIS (Section 3.1.3.2.6.2) spec of \leq 20 mA/ μ sec. (See Figure 1b.1.)

For S/Ns 105-109, the rate of rise of the +28V Main Bus transient load current shall be 250 mA/ μ sec maximum, which exceeds the GIIS (Section 3.1.3.2.6.2) spec of \leq 20 mA/ μ sec. (See Figure 1b.2.)

3.1.3.2.5 DC/DC Converter Frequency

78 kHz for S/Ns 101-104
208 kHz for S/Ns 105-109

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 26

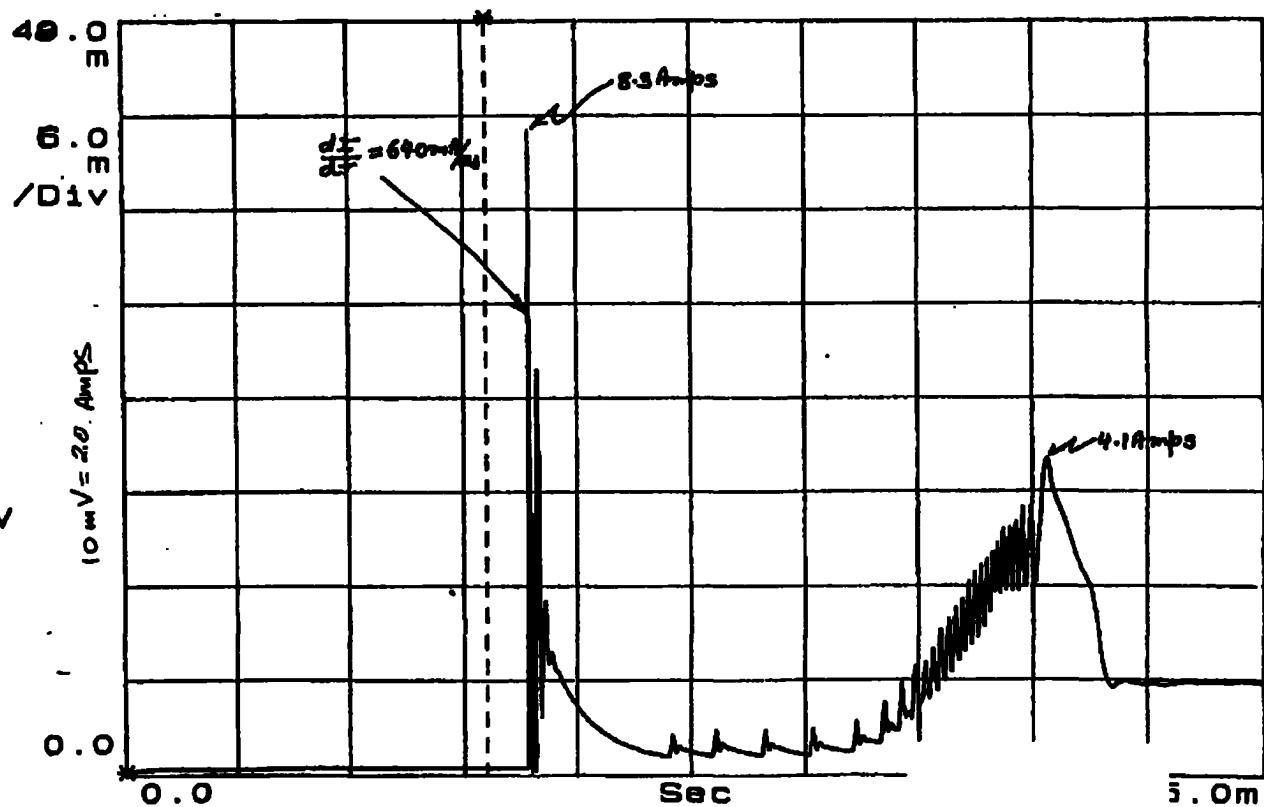


Figure 1a.1. +28 Volt Main Bus Peak Power Worst Case Profile for S/N 101-104

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 27

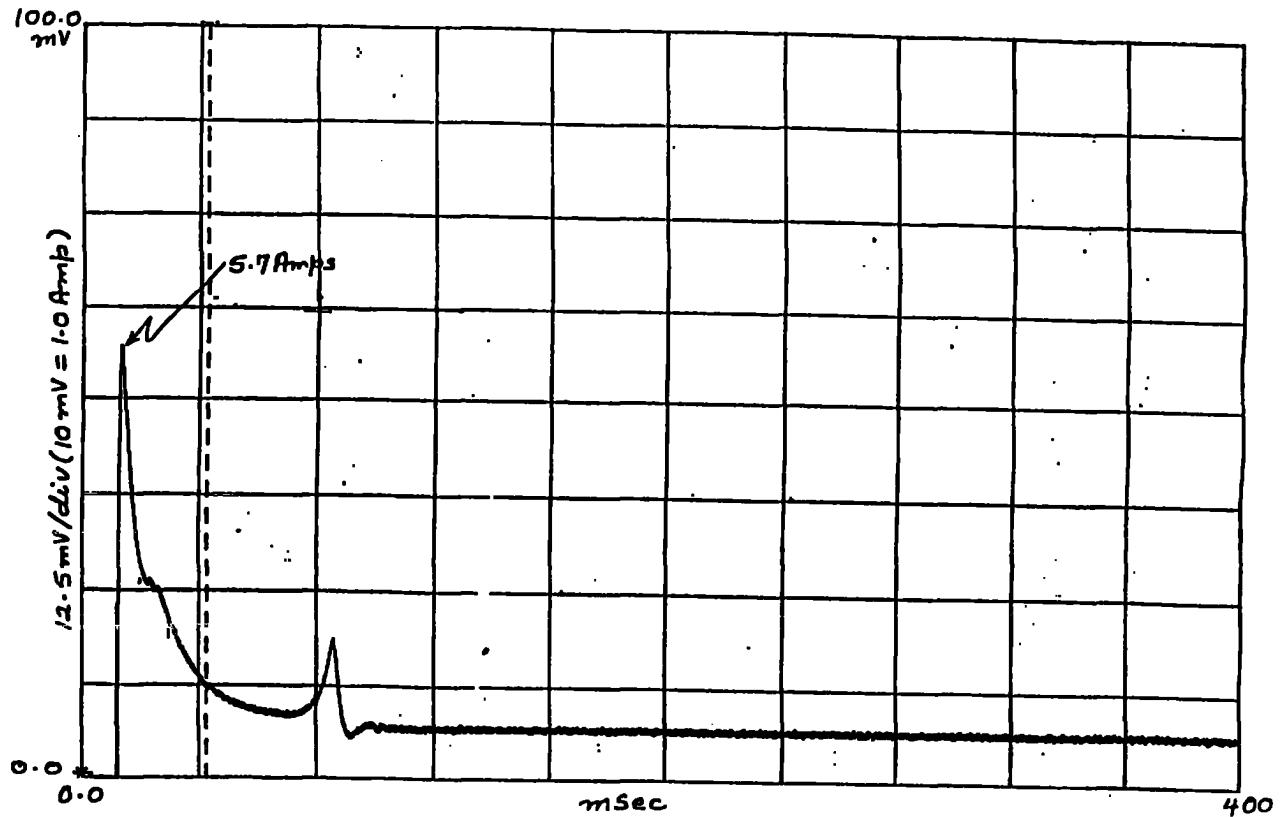


Figure 1a.2. +28 Volt Main Bus Peak Power Worst Case Profile for S/N 105-109

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 28

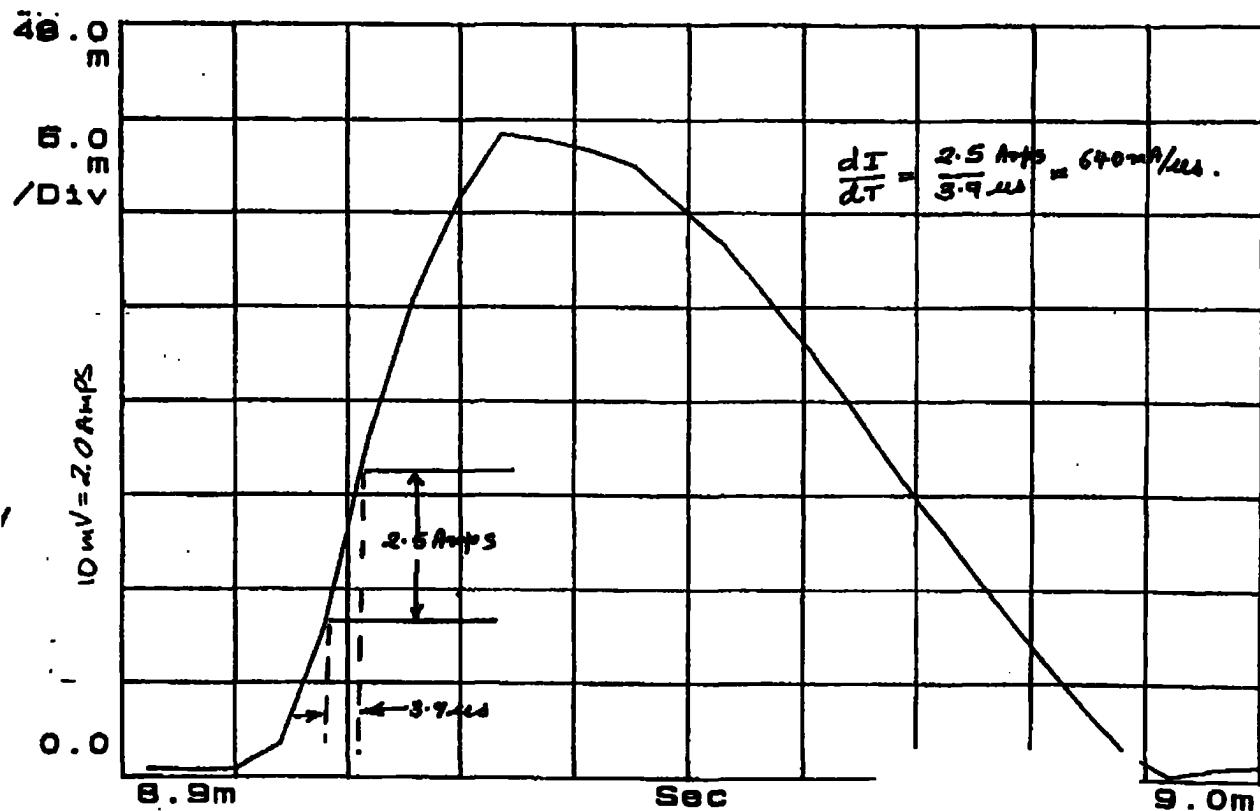


Figure 1b.1. +28 Volt Main Bus Peak Power Worst Case Profile for S/N 101-104

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 29

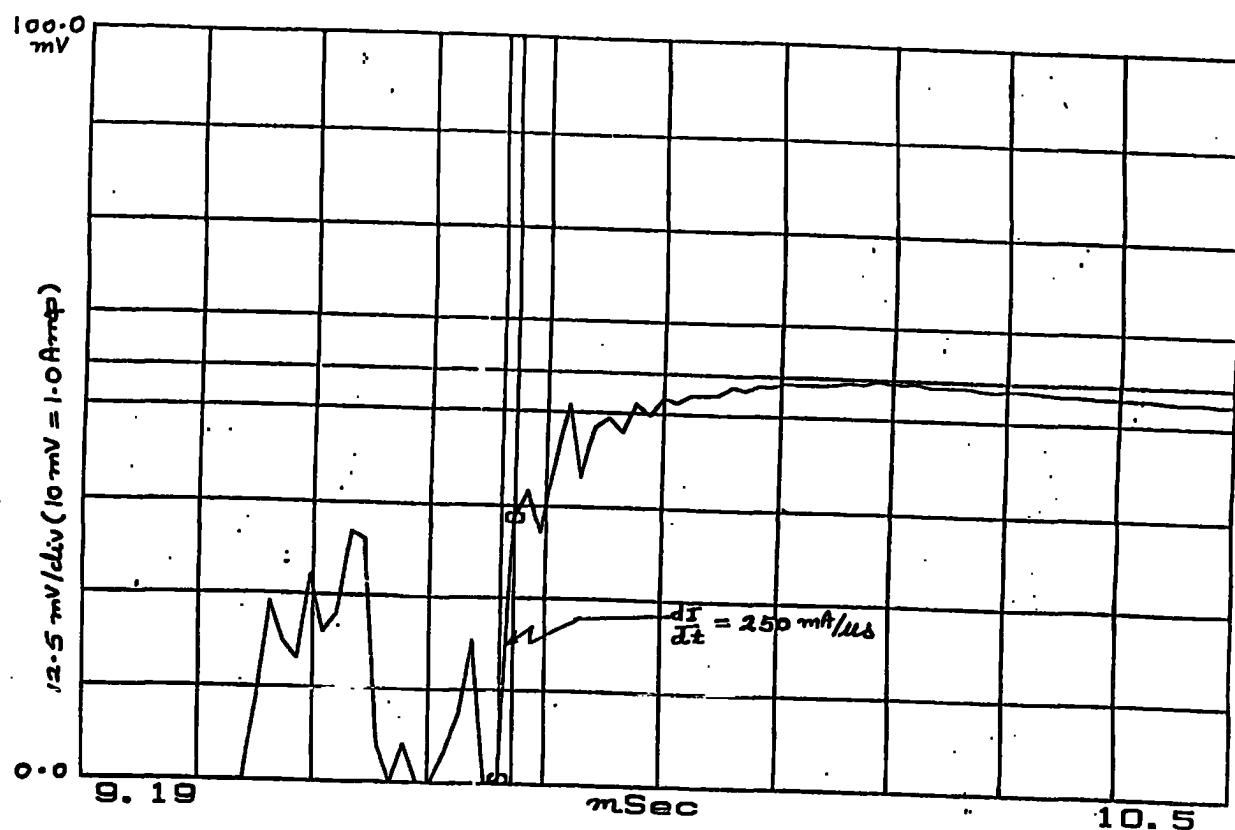


Figure 1b.2. +28 Volt Main Bus Peak Power Worst Case Profile for S/N 105-109

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483

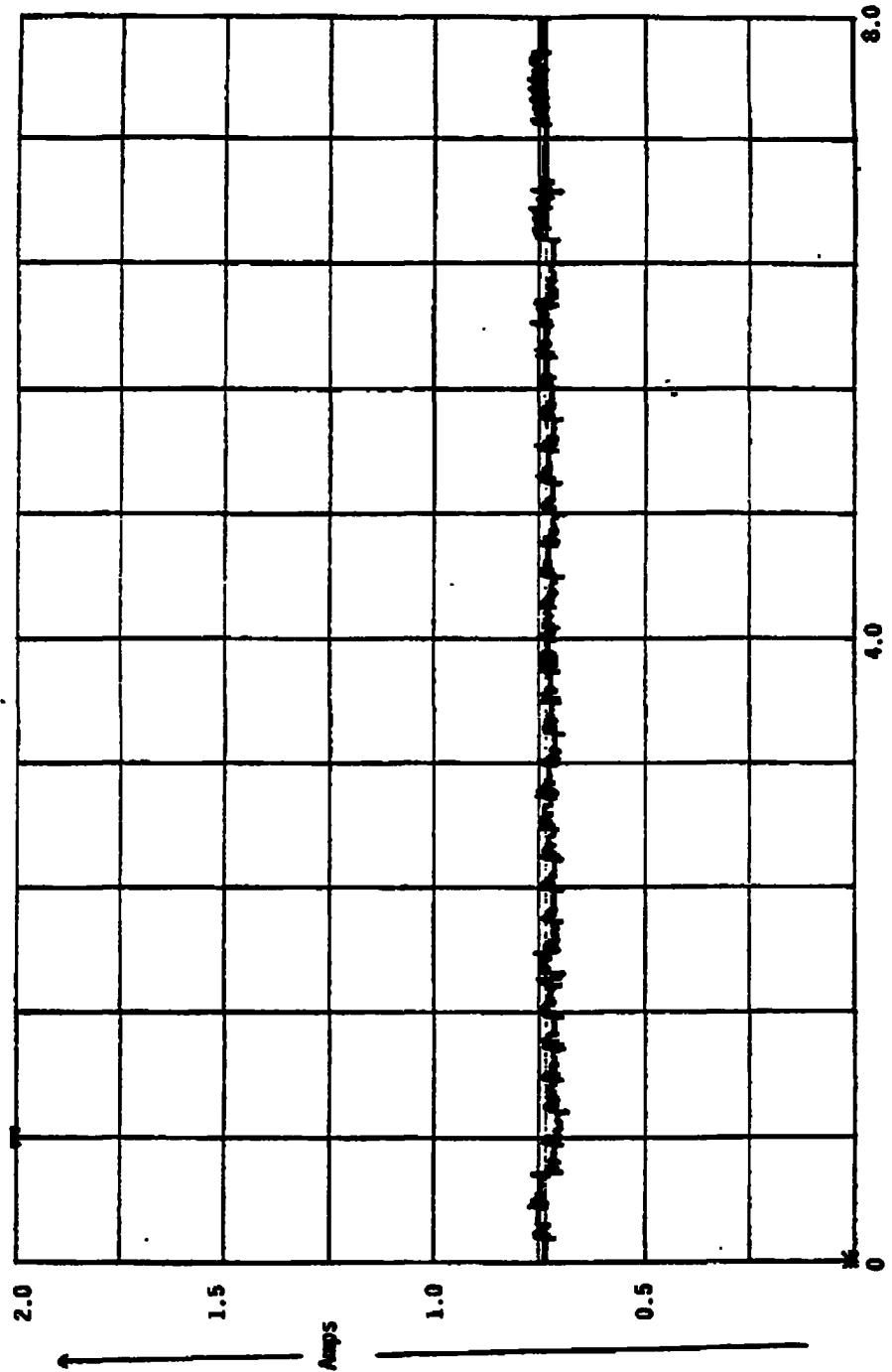


Figure 2. Typical Load Current Ripple

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 31

Refer to Figure 1a and 1b.

Figure 3. Worst Case Transient Load

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 32

Not Applicable
(In normal in-orbit operation, there is
no change in load currents drawn by
the instrument.)

Figure 4. Typical Load Current Transients

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 33

3.1.3.3 +28-Volt Analog Telemetry Bus Power Requirements

The +28-Volt Analog Telemetry Bus may be used for telemetry information which is needed when the instrument is not powered and which is not critical to the mission if this Bus is lost. Other analog telemetry should be powered from the 28-Volt Main Bus.

3.1.3.3.1 Power Dissipation

The power required by the instrument from the +28-Volt Analog Telemetry Bus shall be as shown in Table 4.

There are four telemetry circuits on this bus. The total load is included in the load for the +28-Volt Main Bus (refer to Section 3.1.3.2).

3.1.3.3.2 Power Limiting

The instrument shall limit the short circuit current drain on the spacecraft +28-Volt Analog Bus to 0.01 amperes.

3.1.3.3.3 Transient Loads

The +28-Volt Analog Telemetry Bus will be supplied to all users from a common fused circuit. The worst-case possible loading on this bus produced by all users in combination must fall within the rating of this fused circuit. In order to ensure that this condition is met, any transient load current drawn by the instrument from the +28-Volt Telemetry Bus, including initial power application and instrument turn-on, shall not exceed 150% of the maximum average steady-state current.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483

3.1.3.4 +28-Volt Pulse Load Bus Power Requirements

3.1.3.4.1 Power Dissipation

- (1) The power required by the instrument from the +28-Volt Pulse Load Bus shall be as given in Table 4.
- (2) The heater power required by the instrument, during the on-orbit non-operating condition, from the +28-Volt Pulse Load Bus shall be 14 watts (to maintain L.O. temperatures above -20°C).
- (3) The peak power worst-case profile on the +28-Volt Pulse Load Bus for this instrument shall be as shown in Figure 5. This occurs only during the turn-on following the Module Disconnect command shutdown (i.e., instrument not powered down in the normal way via Module Totally off).

3.1.3.4.2 Power Limiting

- (1) The instrument will be serviced by a 5 ampere rated fuse in the spacecraft.
- (2) The instrument will not limit the short circuit current drain on the spacecraft +28-Volt Pulse Load Bus.

3.1.3.4.3 Transient Loads

- (1) See GIIS (IS-3267415) Sections 3.1.3.4.6.1 and 3.1.3.4.6.2.
- (2) The worst case peak current on the +28V Pulse Load Bus occurs during instrument turn-on following an abnormal (Module Disconnect) shutdown (see Figure 5a) and is 9.6 amps maximum, which exceeds the GIIS spec of ≤ 1.0 amps maximum. (This transient does not occur during normal turn-on.)
- (3) The rate of rise of the +28V Pulse Load Bus transient associated with instrument turn-on following an abnormal shutdown (see Figure 5b) is 846 mA/ μ sec, which exceeds the GIIS spec of ≤ 30 mA/ μ sec.
- (4) Typical waveforms, including transients, for load currents drawn from the +28-Volt Pulse Load Bus during the instrument operational mode (motor stepping, survival heaters off) shall be as shown in Figure 6.
- (5) Motor current loads during the scan cycle will reach 2.2 amps, which exceeds the GIIS spec of ≤ 1.0 amp maximum (absolute) for a period of one second or less. (See Figure 6). Typical motor start-up current loads shall be as shown in Figure 7.
- (6) The ripple on the +28V Pulse Load Bus, during scan operation, shall not exceed 280 mA.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 35

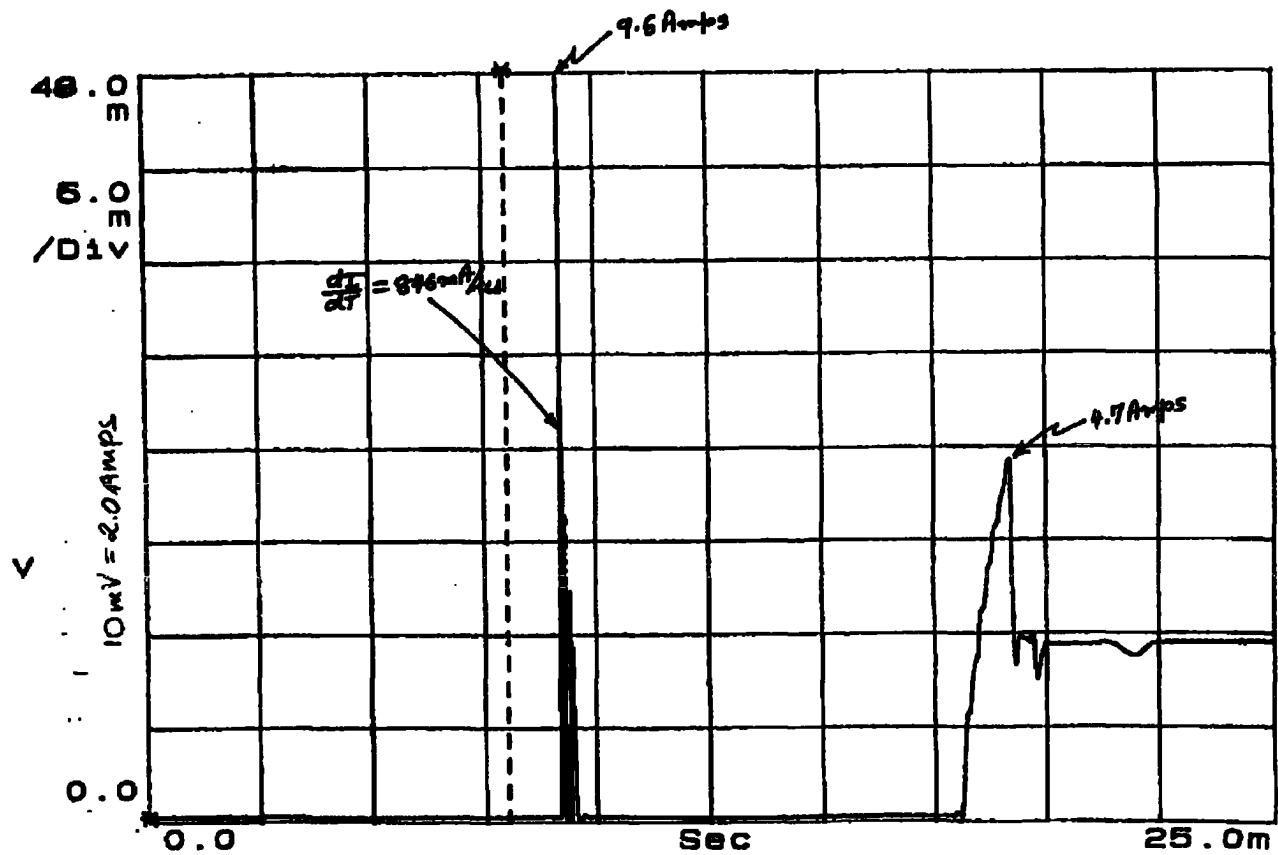
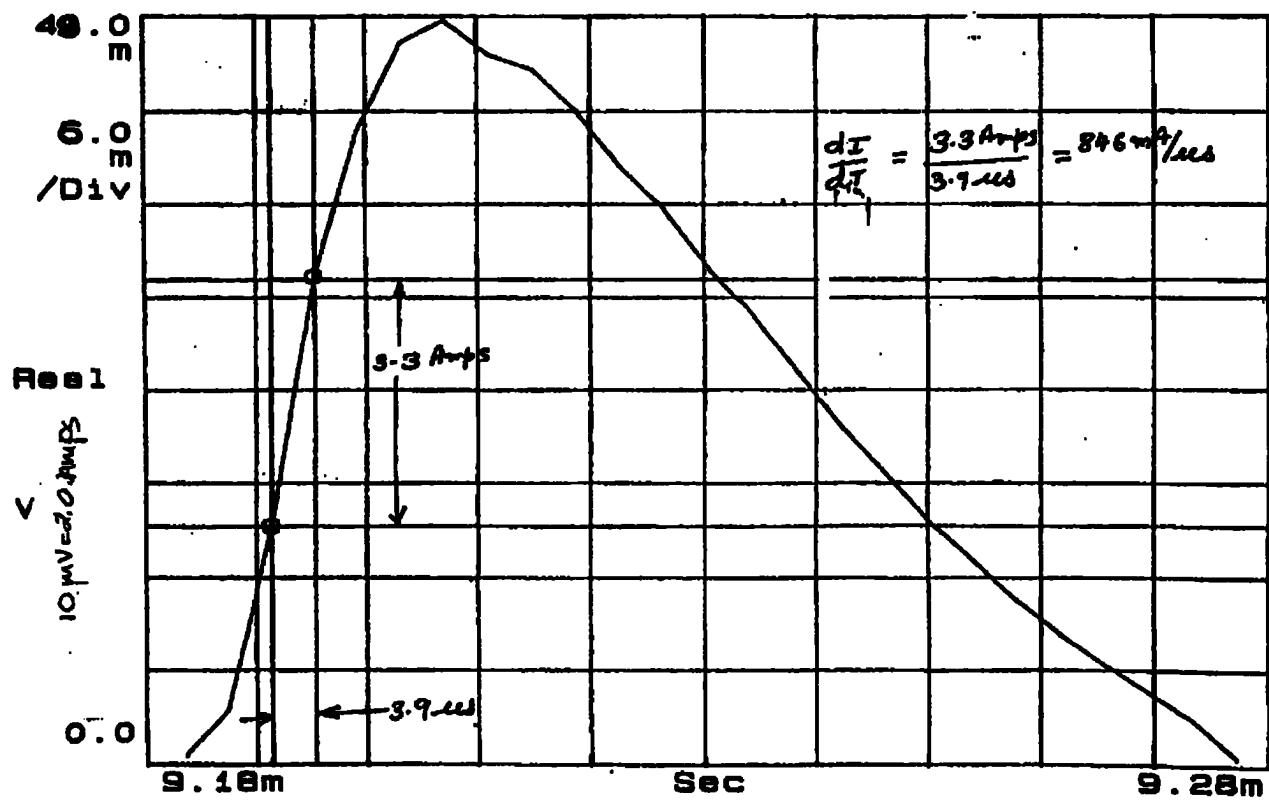


Figure 5a. +28-Volt Pulse Load Bus Peak Power Worst-Case Profile

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 36



ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 37

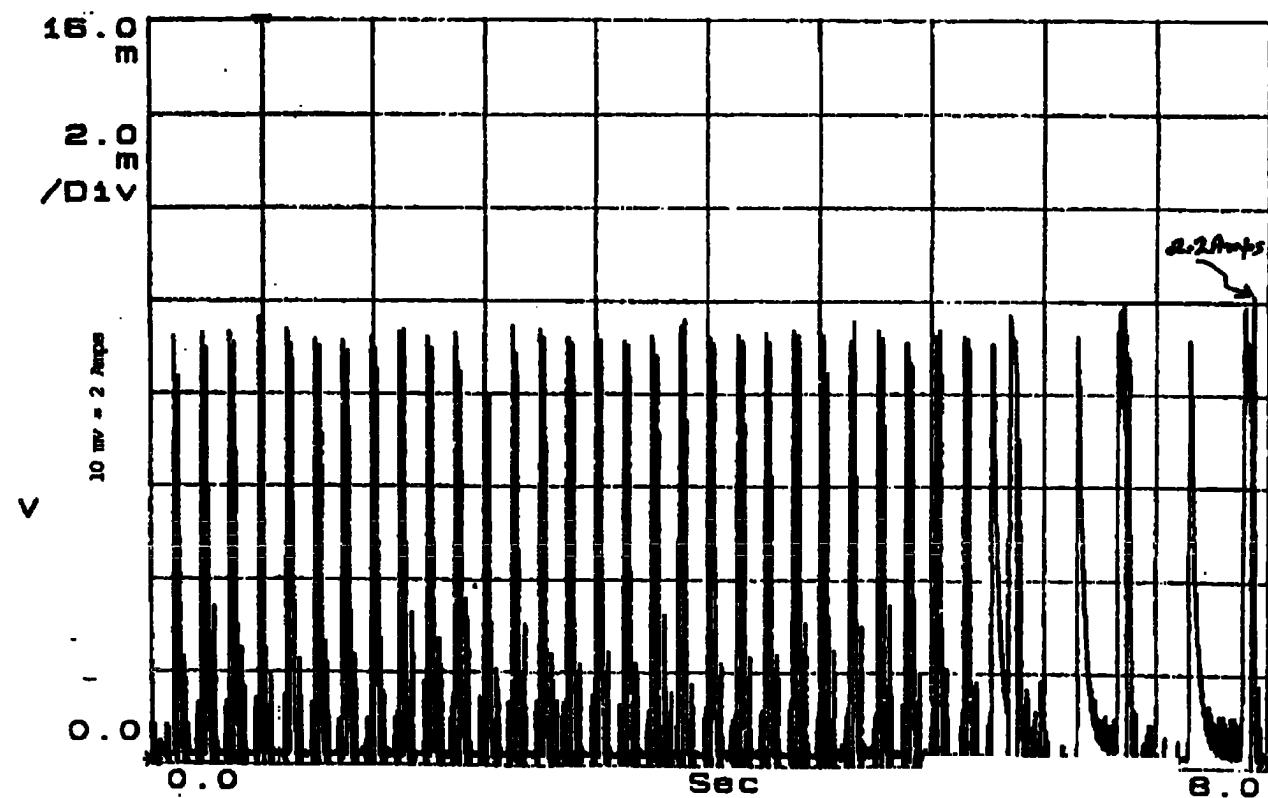


Figure 6. +28-Volt Pulse Load Bus Typical Load Current Waveforms

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 38

Refer to Figure 6

Figure 7. Typical Motor Start-Up Current Loads

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 39

3.1.3.5 +10.0-Volt Interface Bus Power Requirements

3.1.3.5.1 Power Dissipation

The power required by the instrument from the +10.0-Volt Interface Bus shall be as given in Table 4.

3.1.3.5.2 Power Limiting

The instrument shall limit the short circuit drain from the spacecraft +10-Volt bus to 100 milliamperes by use of the RC filter described in Section 3.1.3.5 of the General Instrument Interface Specification, IS-3267415.

3.1.3.5.3 Transient Loads

- (1) Load current transients drawn by the instrument shall not exceed 125% of the maximum steady state current drawn from the +10-Volt bus and shall not exceed 50 milliseconds in duration.
- (2) Typical load current transients and ripple shall be as shown in Figure 8.

3.1.3.5.4 Exceptions

The +10V Bus is used for Digital B signals which must correctly indicate power status with the instrument power off (Ref. GIIS Section 3.1.3.5). The interface circuit is shown on Figure 9.

The +10V Interface Ground and Signal Ground as described in GIIS Section 3.1.1.1 have a common ground (S/N 102-104).

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 40

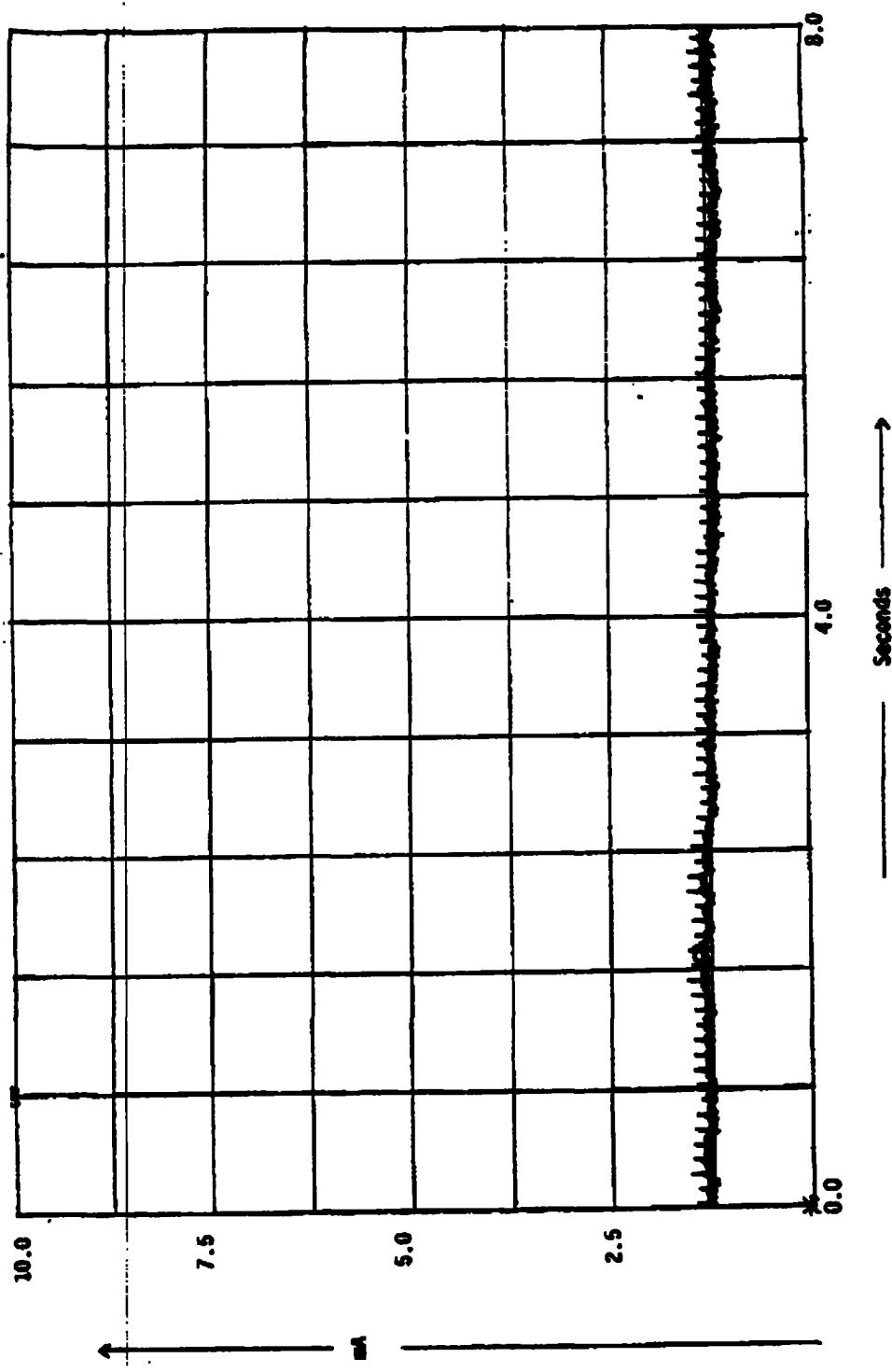


Figure 8. Typical 10-Volt Bus Load Current Transients and Ripple

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 41

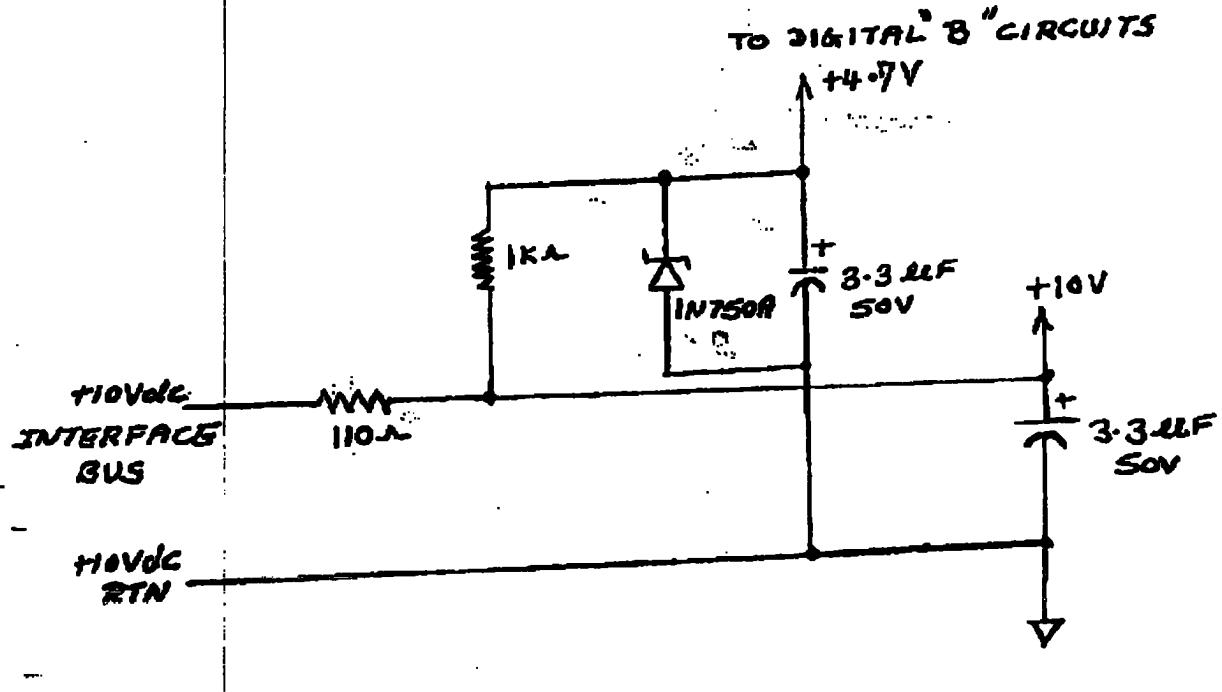


Figure 9. Schematic Diagram of Digital B Power Supply

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 42

3.1.3.6 Power Exceptions

The instrument shall conform to the power requirements of Section 3.1.3 of the General Instrument Interface Specification, IS-3267415. The exceptions to the above specification are as follows:

- (1) 3.1.3.2.3 The load current ripple on the +28V Main Bus exceeds two percent of the maximum average steady-state current. (See Figure 2.)
- (2) 3.1.3.2.4 For S/Ns 101-104, the peak current on the +28V Main Bus is 8.3 amps (maximum). (See Figure 1a.1.) For S/Ns 105-109, the peak current on the +28V Main Bus is 5.7 amps (maximum). (See Figure 1a.2.)
- (3) 3.1.3.2.4 For S/Ns 101-104, the rise time on the +28V Main Bus is 640 mA/μsec (maximum). (See Figure 1b.1.) For S/Ns 105-109, the rise time on the +28V Main Bus is 250 mA/μsec (maximum). (See Figure 1b.2.)
- (4) 3.1.3.4.3 The peak current on the +28V Pulse Load Bus associated with instrument turn-on following an abnormal shutdown is 9.6 amps (maximum). (See Figure 5a.) (This transient does not occur during normal turn-on.)
- (5) 3.1.3.4.3 The rise time on the +28V Pulse Load Bus associated with instrument turn-on following an abnormal shutdown is 846 mA/μsec (maximum). (See Figure 5b.)
- (6) 3.1.3.4.3 The peak current on the +28V Pulse Load Bus is 2.2 amps (maximum). (See Figure 6.)
- (7) 3.1.3.4.3 The +28V PLB current ripple shall not exceed 280 mA.
- (8) 3.1.3.5.4 The +10V Bus is used for Digital B signals which must correctly indicate power status with the instrument power off.
- (9) 3.1.1.1 The +10V Interface Ground and Signal Ground have a common ground (S/N 102-104).

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 43

3.1.4 Input Timing and Control Signals

The spacecraft shall provide the following input timing and control signals to the instrument. See Figure 10A.

3.1.4.1 Clocks

The spacecraft clocks used by the AMSU-A2 shall be as shown in Table 5. The characteristics of these clock lines are detailed in Section 3.1.4.3 of the General Instrument Interface Specification, IS-3267415.

The function of these clocks in the instrument shall be as follows:

- (1) 1.248 MHz - Synchronization of timing of instrument functions to the spacecraft clock.
 - a) Signal Processing
 - b) DC/DC Converter Frequency

3.1.4.2 Synchronization Signals

The spacecraft synchronization signals used by the AMSU-A shall be as shown in Table 6. The characteristics of these sync signals are detailed in Section 3.1.4.4 of the General Instrument Interface Specification, IS-3267415.

The functions of these sync signals in the instrument are as follows:

- (1) Major Frame - Not Used
- (2) 128-Second Sync - Not Used
- (3) 256-Second Sync - Not Used
- (4) 8-Second Sync - To Synchronize the instrument output data format with the start of each AIP frame.
- (5) A₁ Data Enable Pulse - enables readout of AIP minor frame words.
- (6) C₁ Data Clock - clocks the instrument output data into the AIP.

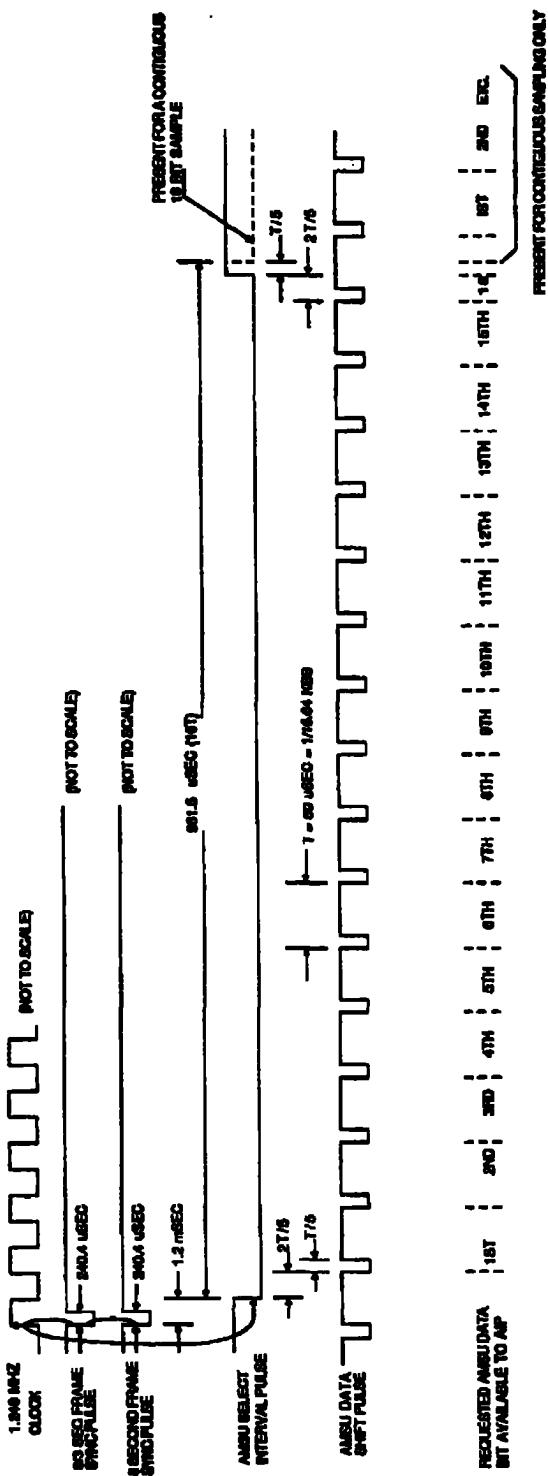
3.1.4.2.1 AIP Switchover

The AMSU-A2 will continue to operate in specification if one side of the AIP fails; but if the redundant side starts up with a random phase 8 second sync with respect to the original sync, then the instrument will be out of sync.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 44

AIP AWMSU DATA INTERFACE (16.64 KBS)



- NOTES:
- (1) LOGIC 1 (ACTIVE LEVEL) = GROUND.
 - (2) INSTRUMENT DATA OUTPUT INTERFACE TO BE ACTIVE ONLY DURING SELECT INTERVAL PERIOD.
 - (3) THROUGH STANDARD RATE INTERFACE WILL BE USED FOR TRANSFER OF ALL DATA AND CONTROL SIGNALS.
 - (4) GROUND REFERENCED TO INTERFACE GROUND.
 - (5) AMBU SELECT AND SHIFT PULSES ARE CLOCKED BY 1 LOW TO HIGH TRANSITION OF THE 1.24MHz CLOCK AND BY THE HIGH TO LOW TRANSITION OF THE 8 SECOND SYNC PULSE.
 - (6) DELAY FROM THE 8 SEC SYNC PULSE TO THE AMBU SELECT INTERVAL PULSE IS 1.23msec + 30usec +/- 30usec FOR A1, AND 20.3msec +/- 30usec FOR A2.

- NOTES:
- (1) LOGIC 1 (ACTIVE LEVEL) = GROUND.
 - (2) INSTRUMENT DATA OUTPUT INTERFACE TO BE ACTIVE ONLY DURING SELECT INTERVAL PERIOD.
 - (3) THROUGH STANDARD RATE INTERFACE WILL BE USED FOR TRANSFER OF ALL DATA AND CONTROL SIGNALS.
 - (4) GROUND REFERENCED TO INTERFACE GROUND.
 - (5) AMBU SELECT AND SHIFT PULSES ARE CLOCKED BY 1 LOW TO HIGH TRANSITION OF THE 1.24MHz CLOCK AND BY THE HIGH TO LOW TRANSITION OF THE 8 SECOND SYNC PULSE.
 - (6) DELAY FROM THE 8 SEC SYNC PULSE TO THE AMBU SELECT INTERVAL PULSE IS 1.23msec + 30usec +/- 30usec FOR A1, AND 20.3msec +/- 30usec FOR A2.

Figure 10A. AIP Digital A Interface

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 45

TABLE 5. SPACECRAFT/AMSU-A2 CLOCK INTERFACES

Clock	Signal* Characteristics	Standard Interface	Interface Logic Element	Source	Function*
1.248 MHz	Para. 3.1.4.3.2	High Speed	CD4000 Series	XSU	See Para. 3.1.4.1.

*See Referenced Paragraph in IS-3267415

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 46

TABLE 6. SPACECRAFT/AMSU-A2 SYNCHRONIZATION SIGNAL INTERFACES

Sync	Signal* Characteristics (Para)(1)	Repetition Rate	Pulse Width	Std. Interface (2)	Source
8 sec. Sync	N/A	8 sec	240.4 μsec	B	AIP
A ₁ Data Enable	N/A	7/100 msec	961.5 μsec	B	AIP
C ₁ Data Clock	N/A	16.64 kHz	12 μsec	B	AIP

1. Interface circuits are A = slow, B = fast.
2. C is delayed 10-20 μsec from A₁. (Nominal Delay 12 μsec)
3. The jitter specification between the 8 sec sync and the A₁, C₁, clocks shall be 50 ns maximum.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483

3.1.4.3 Commands

3.1.4.3.1 General Requirements

The spacecraft shall provide the command inputs listed below to the AMSU-A2. The general characteristics of these commands are detailed in Section 3.1.4.2 of the General Instrument Interface Specification, (IS-3267415).

For "Level" commands, the "ON," "TRUE," or "LOW" level shall be indicated by a logic "1" or zero-volt level. The "OFF," "FALSE," or "HIGH" level shall be indicated by a Logic "0" or +10 volt level for CMOS logic.

The AMSU-A2 shall be provided 4 pulse discrete and 9 level discrete commands. The total number of commands required by the AMSU-A2 shall be 13.

The pulse discrete commands shall have a pulse width of 60 \pm 5 milliseconds, which is adequate for operating relays. The pulse discrete and level discrete commands shall be supplied from separate eight bit parallel output buffers.

All commands shall be individually verified through Digital B telemetry except for the Module Totally OFF and Module Power Disconnect commands which have a common Digital B indicator.

The spacecraft level AMSU-A2 command mnemonics will be as shown in Table 7.

Further details on the functions of each command are given in Table 7 and in the following paragraphs.

3.1.4.3.2 Command Description

PULSE DISCRETES:

- 1) MODULE POWER DISCONNECT. Pulse discrete command. A negative going pulse used to pulse the "off" coil of the latching relay which controls the 28 VDC regulated and 28 VDC pulsed power. Immediately removes all 28 VDC excitation from the instrument. Antenna position is unknown. State of power control relays unchanged. Highest priority command.
- 2) MODULE POWER CONNECT. Pulse discrete command. A negative pulse used to pulse the "on" coil of the latching relay which controls the 28 VDC regulated and 28 VDC pulsed power.
- 3) SURVIVAL HEATER POWER OFF. Pulse discrete command. A negative pulse used to pulse the "off" coil of the latching relay which controls the survival heaters.
- 4) SURVIVAL POWER HEATER ON. Pulse discrete command. A negative pulse used to pulse the "on" coil of the latching relay which controls the survival heaters.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 48

NOTE: The operation of the survival heaters is controlled solely by the spacecraft. The instrument computer has no control upon its operation.

MICROPROCESSOR PROCESSED COMMANDS - LEVEL DISCRETE

- 5) MODULE TOTALLY OFF. Level discrete command. Position antennas to Warm Cal position. Turn both scanner and compensation motor power to off. Remove power to both the 28 VDC regulated and pulsed busses. ϕ = Not Off, 1 = off.

NOTE: If the MODULE POWER DISCONNECT command is commanded to the OFF state and then the MODULE TOTALLY OFF command is commanded to the OFF state, then the MODULE TOTALLY OFF command will be ignored.

- 6) SCANNER A2 POWER (ON/OFF). Level discrete command. Commands the control of power to Scanner A2. ϕ = Off, 1 = ON. When Scanner A2 power is off it will be positioned in the Warm Cal Position (automatic).

NOTE: Less than command sequence delay time of 18 seconds may cause an abnormal instrument configuration.

- 7) COMPENSATION MOTOR POWER (ON/OFF). Level discrete command. Commands the control of power to compensation motor. ϕ = Off, 1 = On.

- 8) WARM CAL. Level discrete command. ϕ = No action, 1 = Command both antennas to Warm Cal position.

- 9) COLD CAL. Level discrete command. ϕ = No action, 1 = Command both antennas to Cold Cal position.

- 10) NADIR. Level discrete command. ϕ = No action, 1 = Command both antennas to nadir position.

- 11) FULL SCAN. Level discrete command. ϕ = No action, 1 = Full scan mode.

- 12) Select Cold Cal Position

1. Send FULL SCAN command to NO ACTION (logic 0).
2. Send WARM CAL command to NO ACTION (logic 0).
3. Send COLD CAL command to ON (logic 1).
4. Wait at least 18 seconds.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 49

5. Send COLD CAL POSITION MSB and COLD CAL POSITION LSB command.

<u>MSB</u>	<u>LSB</u>		
0	0	Position 1	6.667° from -Z axis
0	1	Position 2	8.333° from -Z axis
1	0	Position 3	9.999° from -Z axis
1	1	Position 4	13.332° from -Z axis

6. Wait at least 18 seconds.
7. Send COLD CAL command to NO ACTION (logic 0).
8. Send FULL SCAN command to ON (logic 1).

NOTE: Whenever the instrument is powered down and then powered up, the Cold Calibration Position will be reset to default: Cold Cal Position 1 (00).

NOTE: The priority in which the above 8, 9, 10 and 11 commands are executed is (highest to lowest): Full Scan Mode, Warm Cal Mode, Cold Cal Mode, and Nadir Mode.

Compensation motor follows the AMSU-A2 scanner motor in opposite direction.

In the above level discrete commands logic level $\phi = \text{false} = 10 \text{ VDC}$, and logic level $1 = \text{true} = 0 \text{ VDC}$.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 50

TABLE 7. SPACECRAFT/AMSU-A2 COMMAND INTERFACES

#	Command Name	Type	Mnemonic
1	Module Power Disconnect	Pulse	A2MPD
2	Module Power Connect	Pulse	A2MPC
3	Survival Heater Power OFF	Pulse	A2HPF
4	Survival Heater Power ON	Pulse	A2HPN
5	Module Totally OFF	Level	A2MTF/N
6	Scanner A2 Power ON/OFF	Level	A2SPN/F
7	Compensation Motor Power ON/OFF	Level	A2CPN/F
8	Warm Cal	Level	A2WCN/F
9	Cold Cal	Level	A2CCN/F
10	Nadir	Level	A2NAN/F
11	Full Scan	Level	A2FSN/F
12	Cold Cal Position MSB	Level	A2CM0/1
13	Cold Cal Position LSB	Level	A2CL0/1

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 51

3.1.4.4 Exceptions

The Instrument Control Signal Interfaces shall conform to Section 3.1.5 of the General Instrument Interface Specification, IS-3267415. There are no exceptions to the above specification.

NONE

3.1.5 Instrument Output Signals

3.1.5.1 General

The output data signals supplied by the instrument to the spacecraft shall be assignable into three categories -- Digital A (Scientific) Data, Digital "B" Telemetry and Analog Telemetry. The specific signals supplied by the AMSU-A2 shall be as detailed below:

3.1.5.2 Digital A Data

Digital A data is clocked into the spacecraft AIP at a 16.64 Kbps rate by the shift pulse (C_1) whenever the Data Enable Pulse (A_1) is presented to the instrument. The AMSU-A2 data will be in AIP minor frame words 34 through 47.

3.1.5.2.1 General Requirements

- (1) Content: See Figures 10B1-4
- (2) Word Length: 16 bits (two 8 bit bytes)
- (3) Serial Output: 7 16-bit words per 100 msec

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 52

Figure 10B-1. Digital A Data Format - Full Scan Mode

<u>A2 Frame</u>	<u>Byte No.</u>	<u>Parameter</u>
1 - 3		Sync. Sequence (FF Hex)
4		Unit Identification and Serial Number
5		Digital Housekeeping Data 1
6		Digital Housekeeping Data 2
7		Digital Housekeeping Data 3
8		Digital Housekeeping Data 4
9		Reflector, Position 1, MSP, First reading
10		Reflector, Position 1, LSP, First reading
11		Reflector, Position 1, MSP, Second reading
12		Reflector, Position 1, LSP, Second reading
13		Scene Position 1, Channel 1, MSP
14		Scene Position 1, Channel 1, LSP
15		Scene Position 1, Channel 2, MSP
16		Scene Position 1, Channel 2, LSP
17		Reflector, Position 2, MSP, First reading
18		Reflector, Position 2, LSP, First reading
19		Reflector, Position 2, MSP, Second reading
20		Reflector, Position 2, LSP, Second reading
21		Scene Position 2, Channel 1, MSP
22		Scene Position 2, Channel 1, LSP
23		Scene Position 2, Channel 2, MSP
24		Scene Position 2, Channel 2, LSP
25		Reflector, Position 3, MSP, First reading
26		Reflector, Position 3, LSP, First reading
27		Reflector, Position 3, MSP, Second reading
28		Reflector, Position 3, LSP, Second reading
29		Scene Position 3, Channel 1, MSP
30		Scene Position 3, Channel 1, LSP
.		.
.		.
.		.
247		Scene Position 30, Channel 2, MSP
248		Scene Position 30, Channel 2, LSP
249		Reflector, Cold Cal. Position, MSP, First reading
250		Reflector, Cold Cal. Position, LSP, First reading
251		Reflector, Cold Cal. Position, MSP, Second reading
252		Reflector, Cold Cal. Position, LSP, Second reading
253		Cold Calibration 1, Channel 1, MSP
254		Cold Calibration 1, Channel 1, LSP
255		Cold Calibration 1, Channel 2, MSP
256		Cold Calibration 1, Channel 2, LSP
257		Cold Calibration 2, Channel 1, MSP

NOTE :

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 53

Figure 10B-1. Digital A Data Format - Full Scan Mode (Continued)

A2 Frame Byte No.	Parameter	NOTE:					
		1	2	3	4	5	6
258	Cold Calibration 2, Channel 1, LSP	X	X		X		
259	Cold Calibration 2, Channel 2, MSP						
260	Cold Calibration 2, Channel 2, LSP	X	X	X			
261	Temp Sensor 1, MSP						
262	Temp Sensor 1, LSP						
263	Temp Sensor 2, MSP						
264	Temp Sensor 2, LSP						
.	.						
.	.						
297	Temp Sensor 19, MSP						
298	Temp Sensor 19, LSP						
299	Temp Sensor Reference Voltage, MSP						
300	Temp Sensor Reference Voltage, LSP						X
301	Reflector Warm Cal. Position, MSP, First reading						
302	Reflector Warm Cal. Position, LSP, First reading	X	X	X	X		
303	Reflector Warm Cal. Position, MSP, Second reading						
304	Reflector Warm Cal. Position, LSP, Second reading	X	X	X	X		
305	Warm Calibration 1, Channel 1, MSP						
306	Warm Calibration 1, Channel 1, LSP	X	X				
307	Warm Calibration 1, Channel 2, MSP						
308	Warm Calibration 1, Channel 2, LSP	X	X				
309	Warm Calibration 2, Channel 1, MSP						
310	Warm Calibration 2, Channel 1, LSP	X	X				
311	Warm Calibration 2, Channel 2, MSP						
312	Warm Calibration 2, Channel 2, LSP	X	X				

313-315	Sync. Sequence (FF Hex)						
316	Unit Identification and Serial Number						

NOTE 1: In the above table the MSP is the most significant portion of a particular measurement while the LSP is the least significant portion of the particular measurement.

NOTE 2: In the above table the first set of readings for a particular reflector position are made prior to the integration interval, while the second set of readings are made approximately 1/2 way through the integration period.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483	
			Sheet 54

Figure 10B-1. Digital A Data Format - Full Scan Mode (Continued)

A2 Frame <u>Byte No.</u>	<u>Parameter</u>
316 (Cont'd) NOTE 3:	Digital "A" data as read by the spacecraft shall contain an undetermined number of "fill words". These fill words shall be 0001H and will be intermingled with valid data. The Digital "A" data as sent by the instrument shall be such that no valid data of 0001H shall be included.
NOTE 4:	Format of Position data is: DDDDDDDDDDDDDDDEO D = Data E = Error bit, 0 = not in spec, 1 = in spec 0 = zero
NOTE 5:	Format of Radiometer data is: DDDDDDDDDDDDDDDDDO D = Data 0 = zero If A/D latch up flag, then format at the radiometer and Temp. Sensor Data is: 0000000000000000
NOTE 6:	The temperature sensor reference voltage is utilized for temperature sensors 13 through 19 only. It is used for the initial instrument performance test at instrument contractor's facility.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 55

Figure 10B-2. Digital A Data Format - Warm Cal Mode

<u>A2 Frame Byte No.</u>	<u>Parameter</u>	<u>NOTE:</u>
1 - 3	Sync. Sequence (FF Hex)	
4	Unit Identification and Serial Number	X
5	Digital Housekeeping Data 1	X
6	Digital Housekeeping Data 2	X
7	Digital Housekeeping Data 3	X
8	Digital Housekeeping Data 4	X
9	Reflector, Warm Cal. Position, MSP, First reading	
10	Reflector, Warm Cal. Position, LSP, First reading	X X X X
11	Reflector, Warm Cal. Position, MSP, Second reading	
12	Reflector, Warm Cal. Position, LSP, Second reading	X X X X
13	Warm Cal. Position, Channel 1, MSP	
14	Warm Cal. Position, Channel 1, LSP	X X X
15	Warm Cal. Position, Channel 2, MSP	
16	Warm Cal. Position, Channel 2, LSP	X X X
Bytes 9 through 16 are repeated 29 times for a total of 30 data sets.		
249	Temp Sensor 1, MSP	
250	Temp Sensor 1, LSP	
251	Temp Sensor 2, MSP	X X X X
252	Temp Sensor 2, LSP	
.	.	
.	.	
285	Temp Sensor 19, MSP	
286	Temp Sensor 19, LSP	
287	Temp Sensor Reference Voltage, MSP	
288	Temp Sensor Reference Voltage, LSP	X

SEE NOTE FROM FIGURE 10B-1.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 56

Figure 10B-3. Digital A Data Format - Cold Cal Mode

A2 Frame <u>Byte No.</u>	<u>Parameter</u>	NOTE:
1 - 3	Sync. Sequence (FF Hex)	X
4	Unit Identification and Serial Number	X
5	Digital Housekeeping Data 1	X
6	Digital Housekeeping Data 2	X
7	Digital Housekeeping Data 3	X
8	Digital Housekeeping Data 4	X
9	Reflector, Cold Cal. Position, MSP, First reading	
10	Reflector, Cold Cal. Position, LSP, First reading	X X X X
11	Reflector, Cold Cal. Position, MSP, Second reading	
12	Reflector, Cold Cal. Position, LSP, Second reading	X X X X
13	Cold Cal. Position 1, Channel 1, MSP	
14	Cold Cal. Position 1, Channel 1, LSP	X X X
15	Cold Cal. Position 1, Channel 2, MSP	
16	Warm Cal. Position 1, Channel 2, LSP	X X X
Bytes 9 through 16 are repeated 29 times for a total of 30 data sets.		
249	Temp Sensor 1, MSP	
250	Temp Sensor 1, LSP	
251	Temp Sensor 2, MSP	
252	Temp Sensor 2, LSP	X X X X
.	.	
.	.	
285	Temp Sensor 19, MSP	
286	Temp Sensor 19, LSP	
287	Temp Sensor Reference Voltage, MSP	
288	Temp Sensor Reference Voltage, LSP	X

SEE NOTES FROM FIGURE 10B-1.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 57

Figure 10B-4. Digital A Data Format - Nadir Mode

<u>A2 Frame</u>	<u>Byte No.</u>	<u>Parameter</u>	<u>NOTE:</u>
1 - 3		Sync. Sequence (FF Hex)	
4		Unit Identification and Serial Number	X
5		Digital Housekeeping Data 1	X
6		Digital Housekeeping Data 2	X
7		Digital Housekeeping Data 3	X
8		Digital Housekeeping Data 4	X
9		Reflector, Position 15, MSP, First reading	
10		Reflector, Position 15, LSP, First reading	X X X X
11		Reflector, Position 15, MSP, Second reading	
12		Reflector, Position 15, LSP, Second reading	X X X X
13		Nadir Position, Channel 1, MSP	
14		Nadir Position, Channel 1, LSP	X X X
15		Nadir Position, Channel 2, MSP	
16		Nadir Position, Channel 2, LSP	X X X
Bytes 9 through 16 are repeated 29 times for a total of 30 data sets.			
249		Temp Sensor 1, MSP	
250		Temp Sensor 1, LSP	
251		Temp Sensor 2, MSP	
252		Temp Sensor 2, LSP	X X X
.		.	
285		Temp Sensor 19, MSP	
286		Temp Sensor 19, LSP	
287		Temp Sensor Reference Voltage, MSP	
288		Temp Sensor Reference Voltage, LSP	

SEE NOTES FROM FIGURE 10B-1.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 58

TABLE 8. AMSU-A2 DATA WORD DESCRIPTION

Digital Bit	Housekeeping Data, Byte Number 1 Description	
LSB ↑ MSB	0	0
	1	Full Scan Mode. 0 = Not Full Scan, 1 = Full Scan
	2	Warm Cal Mode. 0 = Not in Warm Cal, 1 = Warm Cal
	3	Cold Cal Mode. 0 = Not in Cold Cal, 1 = Cold Cal
	4	Nadir Mode. 0 = Not in Nadir, 1 = Nadir
	5	Cold Cal Position, LSB
	6	Cold Cal Position, MSB
	7	0
Digital Bit	Housekeeping Data, Byte Number 2 Description	
LSB ↑ MSB	0	0.
	1	Scanner A2 Power 0 = Off, 1 = On.
	2	Scanner Compensator Power 0 = Off, 1 = On.
	3	0.
	4	Survival Heater Power 0 = Off, 1 = On
	5	0.
	6	0.
	7	0.
Digital Bit	Housekeeping Data, Byte Number 3 Description	
0	0.	
1	0.	
2	0.	
3	0.	
4	0.	
5	0.	
6	0.	
7	0.	
Digital Bit	Housekeeping Data, Byte Number 4 Description	
0	0.	
1	0.	
2	0.	
3	0.	
4	0.	
5	0.	
6	0.	
7	0.	

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 59

TABLE 8. AMSU-A2 DATA WORD DESCRIPTION (CONTINUED)

AMSU A2 Temp Sensor Assignments

Number Location

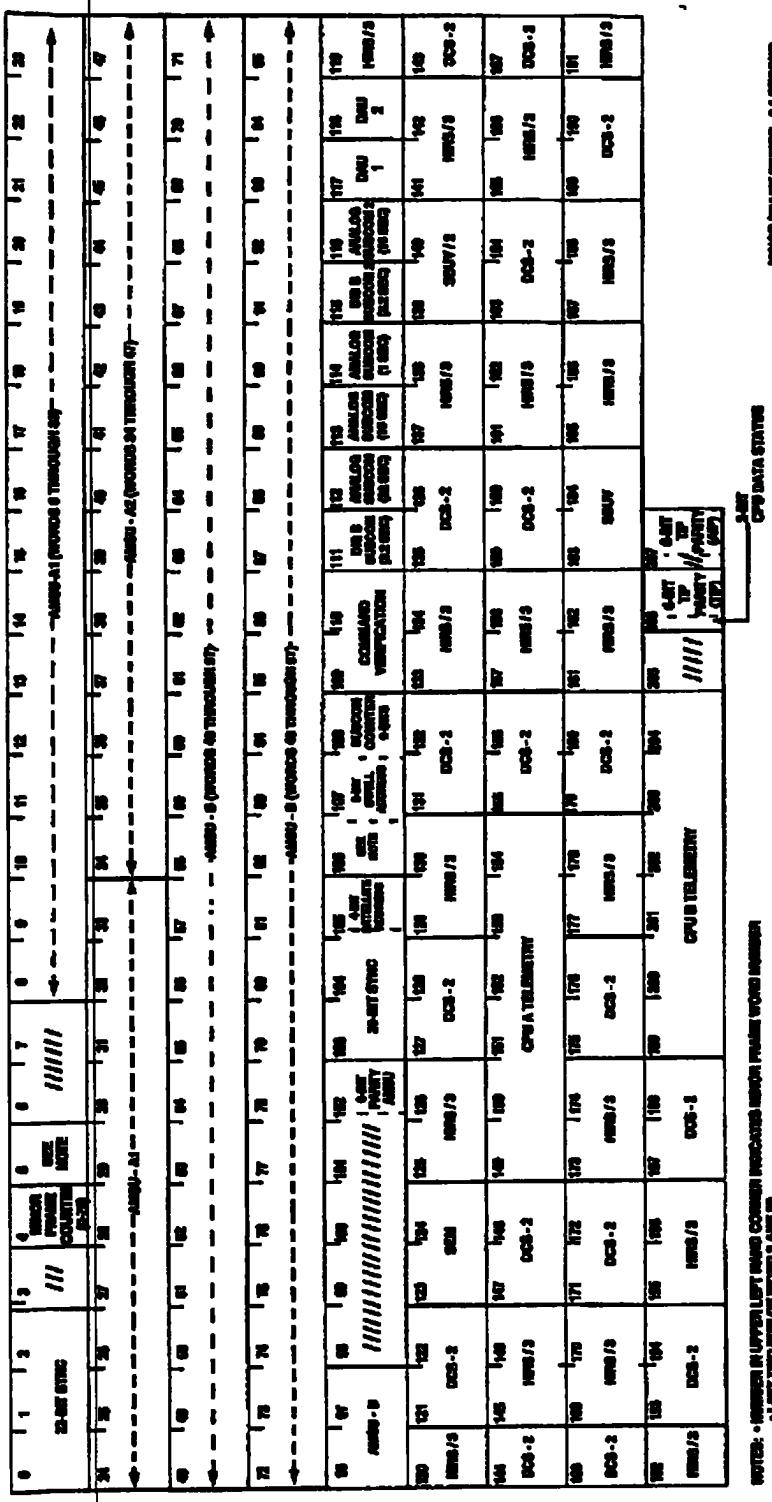
1	Scan Motor
2	Feed Horn
3	RF Mux
4	Mixer IF Amplifier Channel 1
5	Mixer IF Amplifier Channel 2
6	Local Oscillator Channel 1
7	Local Oscillator Channel 2
8	Compensation Motor
9	Subreflector
10	DC/DC Converter
11	RF Shelf
12	Detector/Preamp Assembly
13	Warm load center
14	Warm load 1
15	Warm load 2
16	Warm load 3
17	Warm load 4
18	Warm load 5
19	Warm load 6

AMSU A2 Identification Words

Unit Number	Identification No. (Binary)	S/N
Engineering Model Module A2	00000010	101
Protoflight Model Module A2	00000110	102
Flight Model 1 Module A2	00001010	103
Flight Model 2 Module A2	00001110	104
Flight Model 3 Module A2	00010010	105
Flight Model 4 Module A2	00010110	106
Flight Model 5 Module A2	00011010	107
Flight Model 6 Module A2	00011110	108
Flight Model 7 Module A2	00100010	109

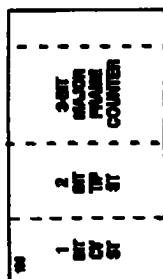
ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 60



MINOR FRAME PATTERN - 6.1 SECURED
OUTPUT DATA RATE - 64 Kbps

NOTES: • NUMBER OF BYTES IN THE LEFT AND CENTER BLOCKS MINOR FRAME WORD NUMBER
• LAST TWO BYTES OF WORD 2 ARE TO
• LOCATE ADDRESS AND STATE AND CONTAIN CODE WORD
• LAST TWO BYTES OF WORD 4 ARE MINOR, LAST TWO BYTES ARE CHECKED CODE WORD
• WORD 6 CONTAINS THE ADDRESS OF THE DESTINATION TO A 16-BIT CONTROL WORD WHICH FIELDS
• WORD 8 CONTAINS THE ADDRESS OF THE DESTINATION TO A 16-BIT CONTROL WORD WHICH FIELDS



ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 61

3.1.5.3 Digital B Telemetry

3.1.5.3.1 General

The Digital B one-bit status telemetry shall be available at the instrument interface at all times. The 3.2 second subcoms generated by the TIP shall sample each Digital "B" Telemetry Point once every 3.2 seconds. The characteristics of the Digital "B" telemetry interface are detailed in Sections 3.1.6, 3.1.8.2, and 3.1.8.3 of the General Instrument Interface Specification (IS-3267415).

Words 8 and 12 of the TIP Minor Frame (AIP Minor Frame Words 111 and 115) will be dedicated to the sampling of Digital B telemetry from all spacecraft components.

3.1.5.3.2 Digital B Telemetry Points

Ten Digital B Telemetry Points are required by the AMSU-A2. The Digital B Telemetry Points provided shall be as shown in Table 9.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 62

TABLE 9. DIGITAL "B" TELEMETRY FOR AMSU-A2

No.	Telemetry Point Name	State*		<u>CH#</u>
		Logic "1"	Logic "0"	
1	Scanner Power ON/OFF**	ON	OFF	31
2	Antenna in Warm Cal Position YES/NO	YES	NO	55
3	Antenna in Cold Cal Position YES/NO	YES	NO	65
4	Antenna in Nadir Position YES/NO	YES	NO	93
5	Full Scan YES/NO	YES	NO	94
6	Module Power**	CONNECT	DISCONNECT	96
7	Compensator Motor ON/OFF**	ON	OFF	99
8	Survival Heater ON/OFF**	ON	OFF	102
9	Cold Cal Position MSB	SEE NOTE		107
10	Cold Cal Position LSB			115

*Logic "1" is a "Low Voltage" State

**Must correctly indicate power status with instrument power off.

NOTE: MSB LSB

0	0	6.667° from -Z
0	1	8.333° from -Z
1	0	9.999° from -Z
1	1	13.332° from -Z

Cold calibration telemetry for digital "B" will be updated within 18 sec. after command receipt.

NOTE: If telemetry points 2, 3, 4 & 5 all indicate Logic "0", the instrument is operating in NO mode. In this mode, ignore digital 'A', analog TLM, and digital 'B' TLM 9 & 10.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 63

3.1.5.4 Analog Telemetry

3.1.5.4.1 General

The Analog Telemetry needed when instrument power is off shall be available at the instrument interface at all times.

Three different subcoms types (32, 16 and 1 second) generated by the TIP will be used to sample all spacecraft analog telemetry. The characteristics of the analog telemetry interface are detailed in Sections 3.1.6, 3.1.8.2, and 3.1.8.3 of the General Instrument Interface Specification (IS-3267415). AMSU-A2 shall use the 16-second analog subcoms.

3.1.5.4.2 Analog Telemetry Points

Analog Telemetry Points used by the AMSU-A2 shall be as shown in Table 10. Descriptions of each telemetry point are detailed below.

The AMSU-A2 shall be provided fifteen analog channels to monitor the health of the instrument.

3.1.5.5 Exceptions

The instrument output signals shall conform to Sections 3.1.6 and 3.1.8 of the General Instrument Interface Specification, IS-3267415. The exceptions to the above specification are as follows:

NONE

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 64

TABLE 10. AMSU-A2 ANALOG TELEMETRY

No.	Telemetry Point Name	Range Scale Factor **	CH# (MNF#)
1	Scanner Motor Temperature*		451 (67)
2	Compensator Motor Temperature*		452 (68)
3	RF Shelf Temperature*		453 (69)
4	Warm Load A2*		455 (71)
5	Compensator Motor Current (Average)		459 (75)
6	Antenna Drive Motor Current (Average)		460 (76)
7	+15 VDC (Signal Processing)		461 (77)
8	+15 VDC (Antenna Drive)		463 (79)
9	-15 VDC (Signal Processing)		466 (82)
10	-15 VDC (Antenna Drive)		468 (84)
11	+8 VDC (Receiver) S/Ns 101-104 +10 VDC (Receiver/Mixer/IF) S/Ns 105-109		469 (85)
12	+5 VDC (Signal Processing)		471 (87)
13	+5 VDC (Antenna Drive)		474 (90)
14	L.O. Voltage Ch 1 (23.8 GHz)		476 (92)
15	L.O. Voltage Ch 2 (31.4 GHz)		477 (93)

* Powered by the +28V Analog TLM Bus

** Instrument S/N unique - to be provided in the instrument calibration book.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 65

3.1.6 Test Points

The test points detailed below shall be used as required by the instrument contractor during test of the AMSU-A2. The AMSU-A2 J7 connector provides test points (outputs) and GSE input commands. (Test points and GSE inputs are listed in Table 11.) These points shall not be used by the spacecraft and shall not be included in the spacecraft harness. The instrument contractor shall supply flight covers for any Test Connectors.

The Test Point Interface shall conform to Section 3.1.7 of the General Instrument Interface Specification, IS-3267415.

3.1.6.1 Input Test Points

Test points used for supplying test signals to the instrument shall be as shown in Table 11.

3.1.6.2 Output Test Points

Test points displaying signals generated within the instrument shall be as shown in Table 11.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 66

TABLE 11. AMSU-A2 TEST POINTS AND GSE INTERFACE
(A2-J7 CONNECTOR)

No.	Function Internal Destination	
1	Chassis GND	
2		
3		
4		
5	I/H, Dump RTN	
6	Dump Signal TP	
7		
8	CH 1 Analog Out TP	000 No Action
9	CH 2 Analog Out TP	001 Cal Scenario #1
10		010 Cal Scenario #2
11		011 Cal Scenario #3
12		100 Cal Scenario #4
13		101 Cal Scenario #5
14		110 Not Used
15		111 Cal Scenario #6
16		
17	GSE CMD LSB	
18	GSE CMD MSB-1	
19	+5V DC GSE Interlock	
20		
21		
22		
23	I/H Signal-TP	
24		
25		
26	Analog Out RTN (2/3)	
27		
28		
29		
30		
31		
32		
33		
34		
35	GSE CMD MSB	
36	GSE CMD RTN (+5V RTN)	
37	+5V DC GSE Interlock	

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 67

3.2 Mechanical Interface

The Instrument Mechanical Interface shall conform to Section 3.2 of the General Instrument Interface Specification, IS-3267415. The exceptions to the above specification are as follows:

The first mode frequency is 82 Hz for S/Ns 101-104 which does not meet the GIIS Paragraph 3.2.9 requirement of greater than 100 Hz.

S/Ns 105-109 meet the first mode frequency of greater than 100 Hz requirement.

3.2.1 Physical Characteristics

3.2.1.1 Dimensions

The nominal outside dimensions of the AMSU-A2 module, including the mounting feet, are shown in Figure 12A. The mounting hole patterns for the AMSU-A2 module shall be as shown in Figure 12B.

The following interface data shall be indicated in the instrument configuration drawing (Aerojet Dwg. No. 1333965):

- (1) Mounting hole location and tolerance
- (2) Connector location and keying
- (3) Center of gravity location
- (4) Inertia - X, Y, and Z axes
- (5) Sunshield location (if one is used)
- (6) Harness tie points
- (7) Identification marking and location
- (8) Ground Strap (if required)
- (9) Location of the optical mirrors
- (10) Reflector location

3.2.1.2 Weight

The total weight of the AMSU-A2 instrument shall not exceed 110.0 pounds.

3.2.1.3 Moments of Inertia

The calculated moments of inertia about the center of gravity of the instrument are as follows:

S/Ns 101-104:

$$I_{xx} = 11500 \text{ lb-in}^2$$

$$I_{yy} = 11300 \text{ lb-in}^2$$

$$I_{zz} = 9500 \text{ lb-in}^2$$

S/Ns 105-109:

$$I_{xx} = 11007 \text{ lb-in}^2$$

$$I_{yy} = 10726 \text{ lb-in}^2$$

$$I_{zz} = 9957 \text{ lb-in}^2$$

These numbers are with the motors not operating.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 68

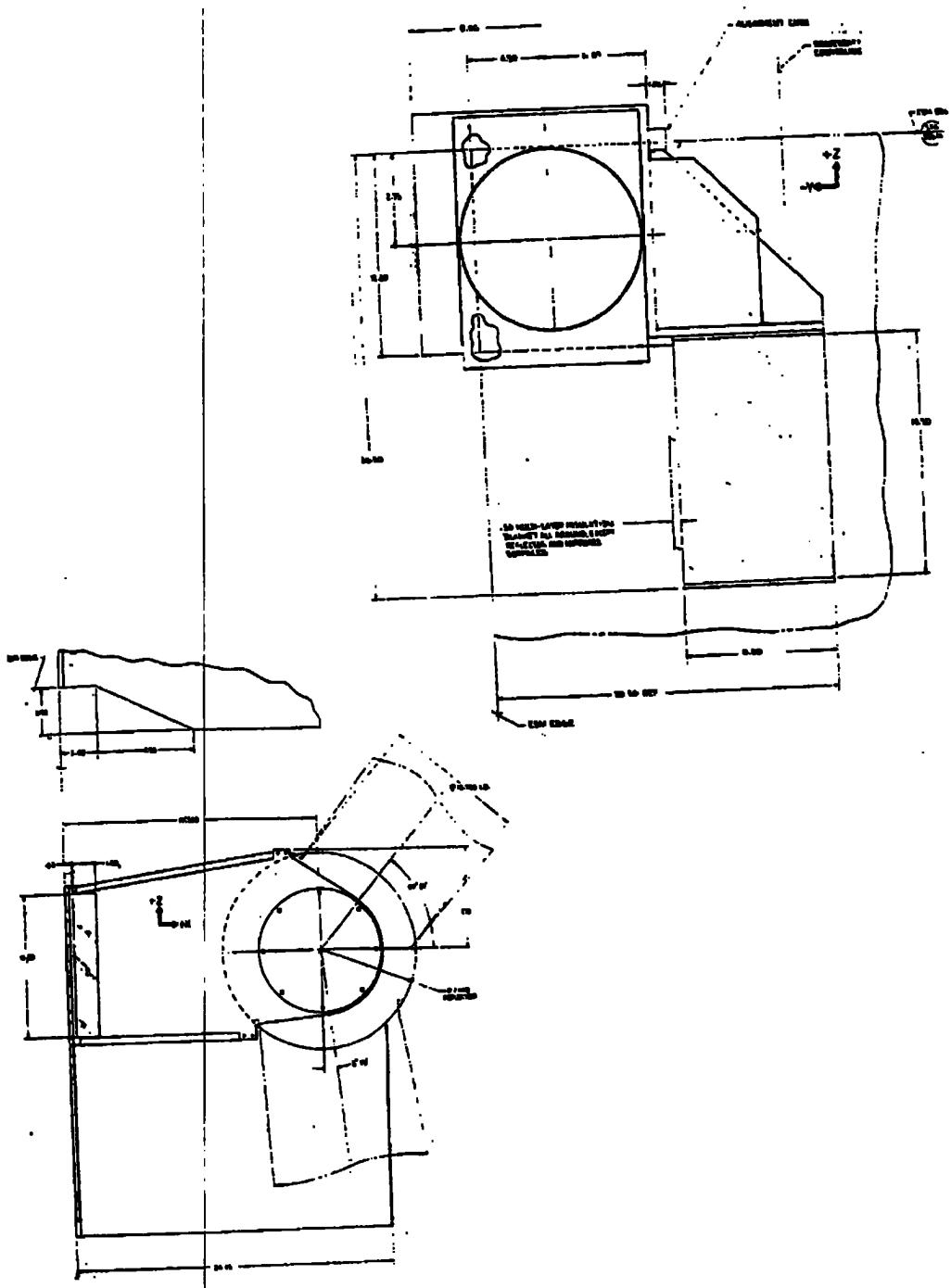


Figure 12A. AMSU-A2 Outline Drawing

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 69

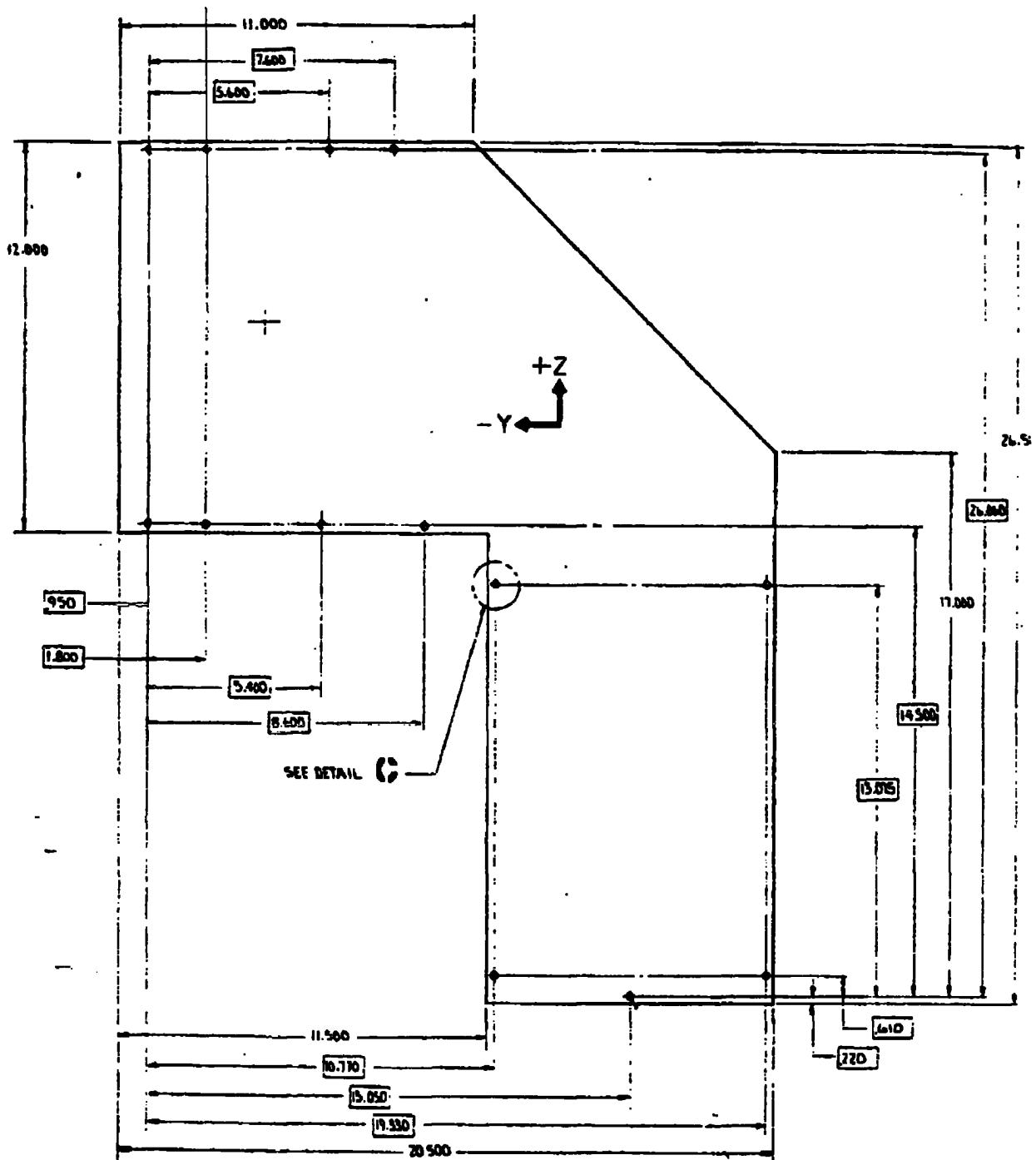


Figure 12B. AMSU-A2 Mounting Hole Locations

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 70

3.2.1.4 Disturbance Torque

The compensated disturbance torque is as shown in Figure 12.

3.2.1.5 Center of Gravity

The maximum distance from the instrument's mounting surface to the center of gravity for the AMSU-A2 modules shall be less than 12.67 inches. The location of the center of gravity shall be as shown on the AMSU-A2 Outline/Interface Control Drawing No. Aerojet 1333965.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 71

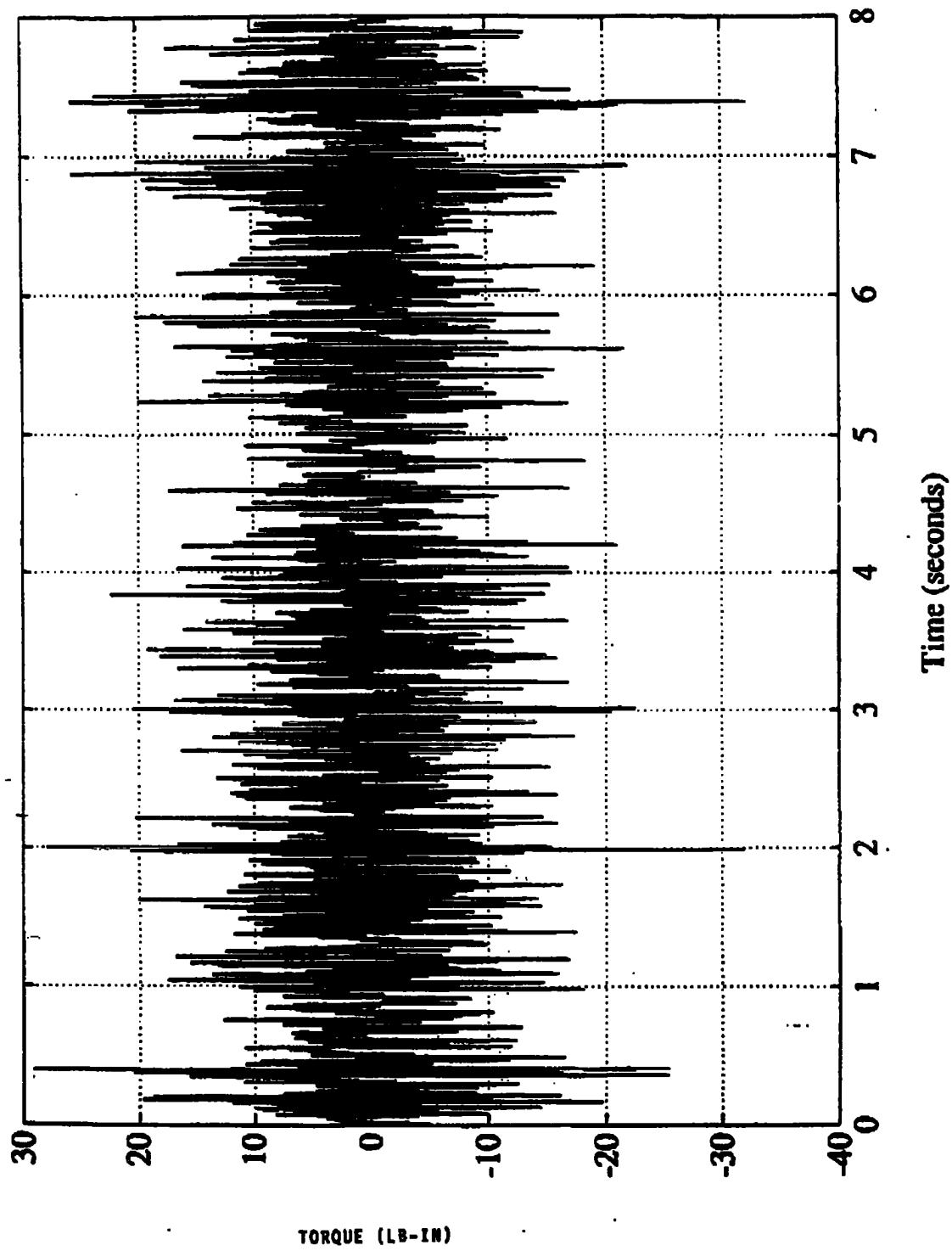


Figure 12C. AMSU-A2 Torque Profile

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 72

3.2.2 Instrument Mounting

3.2.2.1 Instrument Mounting Surface

The instrument mounting flange surfaces shall use the boundaries defined in Para. 3.2.1. It shall be flat within 0.13 mm (0.005 inch) per Section 3.2.2.4 of the General Instrument Interface Specification, IS-3267415. Mounting interfaces on the spacecraft shall be shimmed to within 0.002 inch (max) to minimize instrument flexing.

This instrument shall utilize No. 10 (SPS Technologies 76279) hardware for mounting purposes. AMSU-A2 module will be mounted to a two-piece reinforcement plate which will attach to the ESM earth-facing panel through inserts. The pullout strength of these will be:

TABLE 12. PULLOUT STRENGTH AND SHEAR FORCE OF INSERT IN ESM EARTH-FACING PANEL

	<u>Pullout Strength</u>	<u>Shear Force</u>
SL601 Non-Floating Potted Insert	757 lb	2085 lb

3.2.2.2 Mounting Hole Position

The mounting hole positions shall be defined by the AMSU-A2 drill jig specified below:

<u>Jig</u>	<u>Drawing No.</u>
Spacecraft Pattern	1333071

This jig shall have a reference edge parallel to the spacecraft Y-Y axes.

3.2.2.3 Instrument Location

The AMSU-A2 module's location and orientation on the spacecraft shall be in accordance with the following spacecraft drawings: KLM spacecraft assembly (Dwg. 3278200), ATN-KLM ESM assembly (Dwg. 3278776), and KLM Field of View (Dwg. 3278778).

3.2.2.4 Spacecraft Mounting Surface

The spacecraft mounting surface shall conform to the requirements of Section 3.2.2.3 of the General Instrument Interface Specification, IS-3267415.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 73

3.2.3 Mechanisms

None

3.2.4 Fields-of-View

3.2.4.1 Instrument Requirements

The clear fields-of-view required by the instrument are defined below and as shown in Table 13 and Figures 13A and 13 B. The "Earth", "Nadir", or "+X" direction shall be the "0" degree reference. The spacecraft velocity vector is in the "-Y" direction.

In front of each antenna, there shall be a zone clear of any obstructions. This zone shall be a truncated right circular cone, emanating from the aperture of the antenna, D_A , and expanding with the distance, Z_A , from the aperture according to the expression:

$$D_z = D_A + 2 Z_A \tan \theta_1$$

where D_z is the cone diameter at any distance Z_A and θ_1 is the half cone angle.

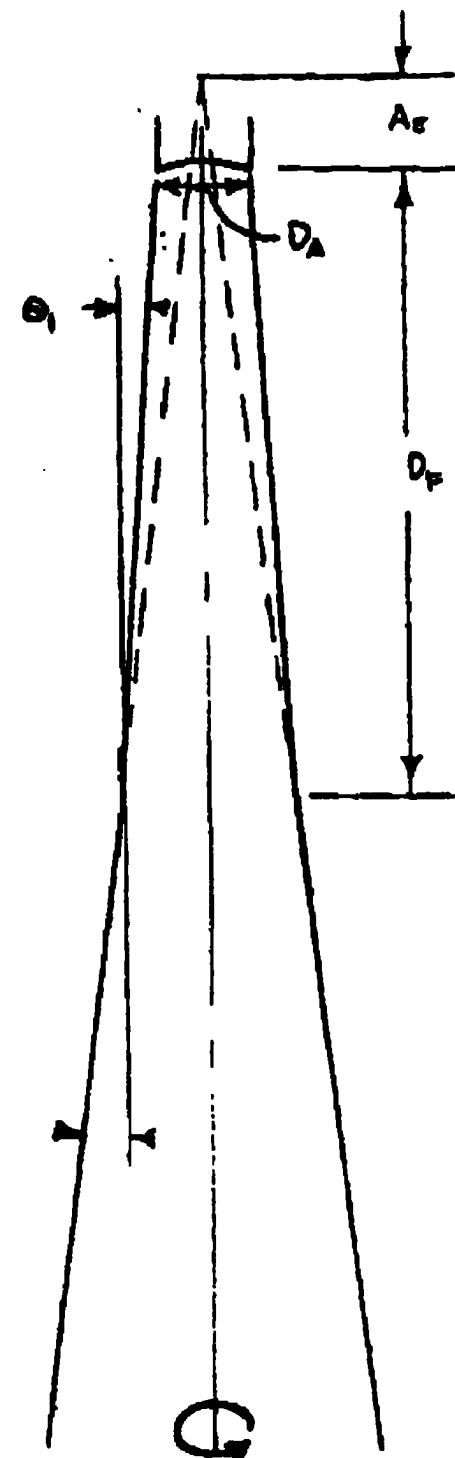
At a distance from the aperture such that Z_A is greater than or equal to D_F , the half cone angle shall be $\theta_2 = 2 \theta_1$.

The aperture is defined as being at a distance A_E in front of the axis of rotation.

Module	D_A (inches)	θ_1 (degrees)	D_F (inches)	A_E (inches)
A2	12	3.50	82	8

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 74



D_A - antenna aperture diameter

A_E - distance to axis of rotation

D_F - distance to full cone angle F.O.V.

θ₁ - $\frac{1}{2}$ = full half-cone angle F.O.V.

θ₂ - full half-cone angle F.O.V.

AMSU:	
A2	
D _A	12"
A _E	8"

$$\theta_2 = 2 \cdot \theta_1$$

$$\theta_1 = 3.5^\circ$$

$$D_F = \frac{D_A/2 - A_E \tan \theta_2}{\tan \theta_2 - \tan \theta_1}$$

Figure 13A. AMSU-A2 F.O.V. Requirement for Both Dimensions

(Crosstrack and down-track) for all beam positions #1 through #30 and cold calibration

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
Sheet 75		

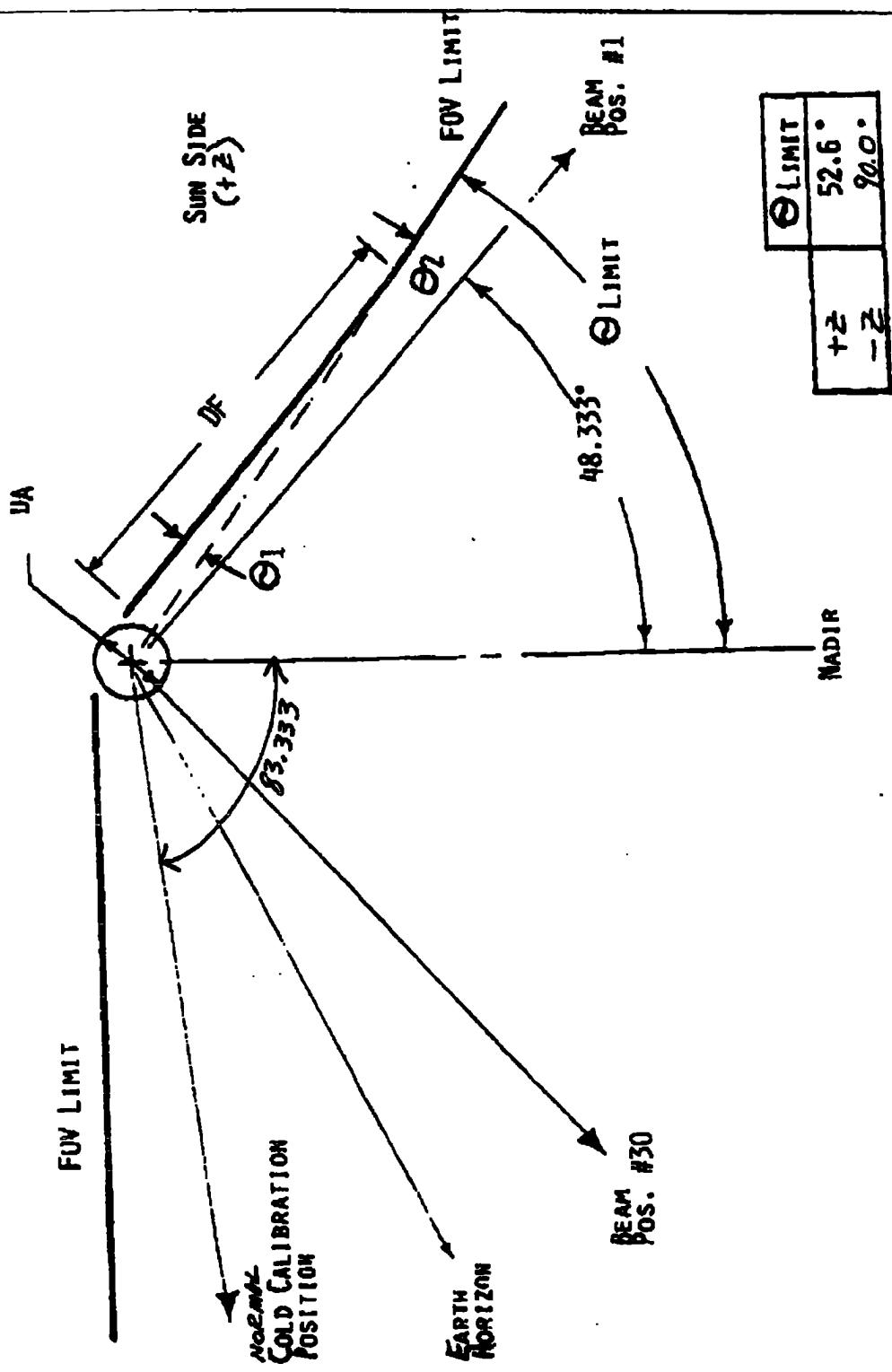


Figure 13B. FOV Crosstrack Scan Profile

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 76

3.2.4.2 Spacecraft Provisions

The spacecraft shall provide unobstructed fields-of-view as defined in Section 3.2.4.1.

3.2.5 Alignment

The instrument alignment shall be in accordance with Section 3.2.3 of the General Instrument Interface Specification, IS-3267415, and shall meet the following requirements:

The in-orbit uncertainties are shown in Table 13A and include uncertainties due to launch, gravity and thermal gradients. The determination of these uncertainties for the AMSU instruments are based on previous analysis. It is expected that the possible movement of the AMSU-A1 and A2 modules due to vibration or launch will be less than shown due to the utilization of shear pins between the module base and the ESM.

To provide for the best possible coregistration between AMSU modules, repositioning of the modules will be required during the initial alignment sequence. The AMSU-A2 module will utilize spacecraft contractor supplied interface plates when mounted to the spacecraft. These plates have been designed to have oversized mounting holes which are required to allow for maximum adjustment (rotation) about the X-axis. The AMSU-B module, as designed, does not allow for maximum adjustment (rotation) about the X-axis. Adjustment of the AMSU-A2 and -B modules about the Y- and Z-axes will be accomplished via shimming. The AMSU-A1 module, as designed, does not allow for maximum adjustment (rotation) about the Z-axis. Adjustment of the AMSU-A1 module about the X- and Y-axes will be accomplished via shimming.

To utilize the available adjustments in the AMSU modules and provide for the best coregistration between modules, the following alignment scenario will be performed:

The AMSU-A1 module will be aligned relative to the primary reference axis (as defined by the ESA) with an initial placement of 0.05 degrees or less in the X- and Y-axes. AMSU-A1 will be placed, accepting the Z-axis position. AMSU-A2 will then be aligned relative to the AMSU-A1 module with an initial placement of 0.05 degrees or less in all three axes. The AMSU-B module will be placed, accepting the X-axis position. AMSU-B will then be aligned relative to the AMSU-A1 module with an initial placement requirement of 0.05 degrees or less in the Y- and Z-axes. The worst case on ground coregistration between the AMSU modules and the ESA will be as shown in Table 13B. Using this method the AMSU modules will be able to meet the in-orbit alignment requirements relative to the primary reference axis as shown in Table 13C with an in-orbit coregistration between the AMSU modules and the ESA as shown in Table 13D.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 77

3.2.5.1 Reference Surfaces

The instrument and alignment reference surfaces (alignment cube) shall be compatible with Section 3.2.3.3 of the General Instrument Interface Specification, IS-3267415.

- (1) Alignment Reference Position with Respect to Optical Axis: Each reference surface shall be placed normal to one of the three planes used to define the instrument optical axis and placed so that it may be sightable from the +Y and +X axes.
- (2) Size: 1" diameter minimum
- (3) Orientation: See Aerojet Drawing No. 1333965
- (4) Flatness: 1/4 wave visible

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 78

TABLE 13A. AMSU ON-ORBIT UNCERTAINTIES (WRT ESA)

INTS.	A	B	C	D	E	F	G	H	I	RSS
A1	0.1	0	0.05	0.0014	0.0014	0.028	0.05	0.025	0.0014	0.1281
A2	0.1	0	0.05	0.0014	0.0014	0.028	0.05	0.083	0.0014	0.1506
B	0.1	0	0.05	0.0014	0.0014	0.028	0.05	0.083	0.0014	0.1506

Instrument

- A: Knowledge of Inst mirror WRT Electrical Boresight axis
- B: Repeatability of Inst mirror placement
- C: Change in Inst Electrical Boresight axis due to Env test

Spacecraft

- D: Measurement tolerance from RPPA to ESA mirror
- E: Repeatability of ESA Mirror
- F: Uncompensated gravitational tolerance between Inst
- G: Change in position due to launch
- H: Change in position due to on-orbit thermal gradients
- I: Measurement tolerance from RPPA to Inst. mirror

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483	
			Sheet 79

TABLE 13B. AMSU INITIAL GROUND COREGISTRATION

Instrument	Initial Placement (Max)	Initial Placement (RSS'D)
ESA/AMSU-A1	0.05°	0.05°
ESA/AMSU-A2	0.10°	0.07°
ESA/AMSU-B	0.10°	0.07°
AMSU-A1/AMSU-A2	0.05°	0.05°
AMSU-A1/AMSU-B	0.05°	0.05°
AMSU-A2/AMSU-B	0.10°	0.07°

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 80

TABLE 13C. AMSU ALIGNMENT REQUIREMENTS (WRT ESA)

INST	Initial Position (1)	Max Alignment Shift Due to Vib (2)	Final Position	Uncertainty (3)	Calculated Requirement
AMSU-A1	<0.05°	±0.05°	<0.1°	±0.13°	0.23°
AMSU-A2	<0.10°	±0.05°	<0.15°	±0.15°	0.30°
AMSU-B	<0.10°	±0.05°	<0.15°	±0.15°	0.30°

(1) Sensor optical axes WRT S/C primary axis

(2) Sensor reference axes WRT S/C primary axes

(3) From RSS'D uncertainty in Table 13A

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483	
			Sheet 81

TABLE 13D. AMSU IN-ORBIT COREGISTRATION

Instrument	Final Position	Uncertainty	In-Orbit Coregistration
ESA/AMSU-A1	0.10°	0.13°	0.23°
ESA/AMSU-A2	0.15°	0.15°	0.30°
ESA/AMSU-B	0.15°	0.15°	0.30°
AMSU-A1/AMSU-A2	0.10°	0.20°	0.30°
AMSU-A1/AMSU-B	0.10°	0.20°	0.30°
AMSU-A2/AMSU-B	0.15°	0.21°	0.36°

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 82

3.2.6 Protective Covers

Protective covers for the antenna shall be required for the AMSU-A2 modules as follows:

Protective covers shall be installed over the rotating portion of the antenna. These covers shall be designed such that the antennas can rotate with the covers in place. These covers shall be non-flight.

These covers shall meet the specifications in Section 3.2.11 of the General Instrument Interface Specification (IS-3267415) with no exceptions granted.

3.2.6.1 Accessibility

Paragraph 3.2.11 if the General Instrument Interface Specification applies without exception.

3.2.6.2 Installation Requirements

Paragraph 3.2.11 if the General Instrument Interface Specification applies without exception.

3.2.6.3 Removal Requirements and Reasons

Protective covers shall be removed at the launch site prior to mating with the launch vehicle fairing. The IS-3267415 requirement for covers which are "removable with one hand at the launch site after complete spacecraft assembly and mating to the launch vehicle" is no longer applicable.

3.2.6.4 Precautions

The handling precautions shall be as specified in AE-26357, AMSU-A1 and -A2 Handling Procedure.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 83

3.2.7 Instrument Materials and Finishes

The instrument materials and finishes shall comply with the General Instrument Interface Specification.

3.2.8 Spacecraft Harness Clamp Requirements

There is no requirement for the instrument vendor to install a spacecraft harness clamp on the instrument. If a harness tie-down clamp is required, it will be potted to the instrument, within the cabling routing zone as indicated on AES Dwg #1333965, at the time of integration of the instrument with the spacecraft.

3.2.9 Marking

Identification and marking shall be in accordance with Section 3.3.7 of the General Instrument Interface Specification, IS-3267415. The following information shall be provided for the AMSU-A2. This marking shall be visible when the instrument is mounted on the spacecraft (with thermal blankets not in place).

Equipment Nomenclature
Serial Number
Contract (or Purchase Order) Number
Manufacturer's Name or Trademark
Manufacturer's Part Number

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 84

3.3 Thermal Interface

The basic characteristics of the instrument/spacecraft (ESM) interface and the requirements necessary to establish and maintain this interface shall be as follows.

3.3.1 Responsibility

3.3.1.1 Instrument Vendor

The instrument vendor shall be responsible for the thermal design of the instrument.

The instrument vendor shall furnish to the spacecraft contractor a complete documentation package clearly defining the physical outline of the instrument, its multilayered insulation blankets, fixed-area radiators, its louver/radiator assemblies (if any) and its mounting scheme. This documentation shall consist of a set of fully annotated drawings. Refer to Section 4.6.3.6 of GSFC-S-480-13 (S/Ns 101-104) and GSFS-S-480-80 (S/Ns 105-109).

The instrument vendor shall furnish to the spacecraft contractor a reduced thermal model of the instrument for the purposes of performing systems level thermal analyses. The requirements for this model shall be established during instrument vendor/spacecraft contractor interface discussions. Refer to Section 4.6.3.6 to GSFC-S-480-13 (S/Ns 101-104) and GSFC-S-480-80 (S/Ns 105-109).

3.3.1.2 Spacecraft Contractor

The spacecraft contractor shall be responsible for enforcing the requirements and restrictions imposed on the thermal interface.

Interface hardware such as mounting brackets, mounting screws, washers, "loose" thermal isolators, reinforcement plates, cable insulation and multilayered insulation blankets used for interfacing purposes shall be the responsibility of the spacecraft contractor.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 85

3.3.2 General Requirements

The thermal design of the instrument package and its implementation therein shall conform to all of the applicable requirements and restrictions specified in Section 3.4 of IS-3267415 (ATN-KLM General Instrument Interface Specification).

The thermal design of the instrument shall provide for minimal thermal coupling between the instrument and the spacecraft structure (ESM). In particular, the net orbit-average energy transfer rate between the instrument package and the ESM shall not exceed the values shown in Figure 14.

Thermal control of the instrument may utilize both passive and active elements.

3.3.3 Instrument Temperature Requirements

The allowable temperature ranges applicable to the instrument shall be as specified in Table 14. The thermal control provided for the instrument shall maintain the designated point-of-application temperature(s) within these ranges when the instrument is situated in the designated environment.

3.3.4 Spacecraft (ESM) Temperature Specifications

The spacecraft component (ESM) of the thermal interface is temperature-characterized as follows.

3.3.4.1 Operational Conditions

<u>ORBITAL SUN-ANGLE</u>	<u>MEAN INTERFACE (ESM) TEMPERATURE (°C)</u>	<u>ORBITAL VARIATION (C°)</u>
0°	13	+1
27.5°	19	+3
80°	23	+3

The interface temperature will be within ± 5 degrees C of the mean value shown. The maximum rate of change of this interface temperature shall not exceed 5 C° per hour at any time on-orbit.

3.3.4.2 Survival (Safestate) Condition

<u>ORBITAL SUN-ANGLE</u>	<u>MEAN INTERFACE (ESM) TEMPERATURE (°C)</u>	<u>ORBITAL VARIATION (C°)</u>
0°	5	+3
27.5°	10	+3
80°	10	+3

The interface temperature will be within ± 5 degrees C of the mean value shown. The maximum rate of change of this interface temperature shall not exceed 5 degrees C per hour at any time on-orbit.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 86

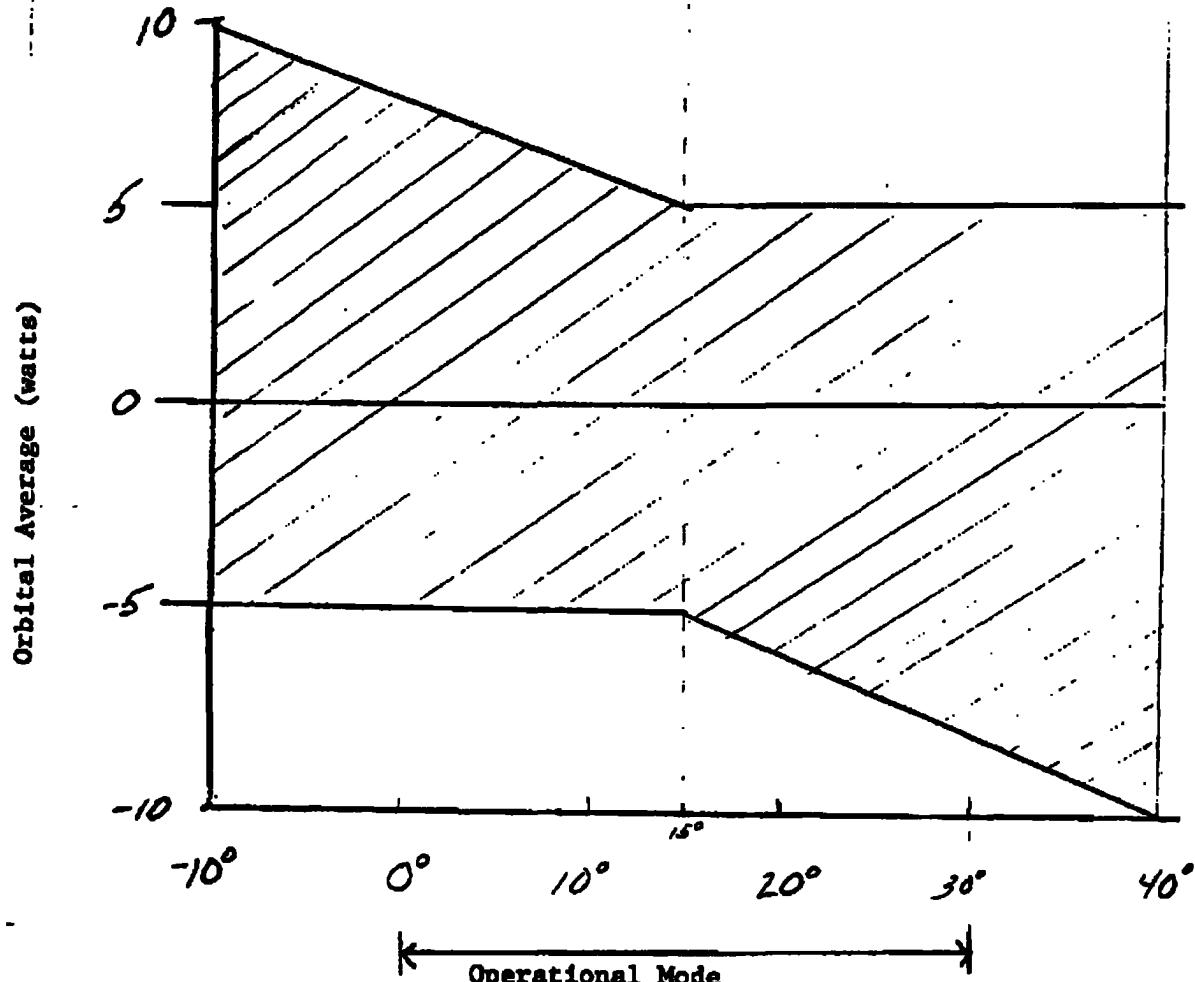


Figure 14. Orbit-Average Energy Transfer

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 87

TABLE 14. INSTRUMENT ALLOWABLE TEMPERATURE RANGES

	<u>Temperature Range Definition</u>	Range Limits (°C)		<u>Application Point</u>
		<u>MIN</u>	<u>MAX</u>	
(1)	Allowable on-orbit operating temperature range; instrument data within specification.	-7*	+30*	Receiver Shelf
(2)	Allowable on-orbit operating temperature range; instrument data not within specification.	-20**	+58***	
(3)	Allowable on-orbit non-operating temperature range; (survival range).	-30** -30**	+66*** +60***	S/Ns 101-104 S/Ns 105-109
(4)	Allowable on-orbit MIN/MAX turn-ON temperatures.	-12	+48	Receiver Shelf
(5)	Allowable in-air long term storage temperature range.	-15	+50	External Surface

*Actual operating temperature range may differ based on actual performance of individual instruments and will be provided in the calibration data book.

**Coldest component.

***Hottest component.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483	
			Sheet 88

3.3.5 Instrument Thermal Control Components

The following passive and active thermal control elements shall be incorporated within the instrument.

3.3.5.1 Passive Control Elements

3.3.5.1.1 Surface Finishes (External) and Fixed Area Radiators

Details for these items shall be as specified in the following documents: Aerojet Dwg No. 1333965

3.3.5.1.2 Multilayered Insulation Blankets

Details for these items shall be as specified in the following documents: Aerojet 1333965

3.3.5.1.3 Mounting

Instrument mounting details shall be as specified in the following documents: Aerojet AE-26154 (Spacecraft Integration for the AMSU-A System).

3.3.5.1.4 Other

NONE.

3.3.5.2 Active Control Elements

3.3.5.2.1 Operational Heaters

None

3.3.5.2.2 Louver/Radiator Assemblies

None

3.3.5.2.3 Survival Heaters

- 1) 56.3 ohms $\pm 5\%$
- 2) Used when instrument is non-operating only
- 3) Ground commandable with a thermostat over temperature shutoff

3.3.5.2.4 Safety Heaters

- 1) 56.3 ohms $\pm 5\%$
- 2) Used at spacecraft integrator's thermal vacuum facility.
- 3) Refer to Table 3A of this document for electrical connection.
- 4) Maximum voltage applied shall be 40 V.
- 5) Thermostat over-temperature shutoff.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 89

3.4 Environmental Interface

The instrument shall conform to Sections 3.5, 3.6, and 3.7 of the General Instrument Interface Specification, IS-3267415.

3.4.1 Magnetic Characteristics

The magnetic characteristics of the instrument shall be in conformance with Section 3.5 of the General Instrument Interface Specification, IS-3267415.

The following magnetic materials are used in the AMSU-A2:

- 1 - Samarium Cobalt - Motor Assembly
- 2 - Ferrite Material - Isolators and Latching Relays

The magnetic environment imposed by the spacecraft shall be as specified in Section 3.5 of the General Instrument Interface Specification, IS-3267415.

3.4.2 EMI

The AMSU-A2 shall conform to Section 3.6 of the General Instrument Interface Specification, IS-3267415. The exceptions to the above specification are as follows:

The AMSU-A2 shall operate without degradation in the presence of the electric field strengths in Table 15.

TABLE 15. RF FIELDS AT AMSU-A2 INSTRUMENT

Spacecraft Antenna	Instrument Antenna (v/m)	Frequency (MHz)
BDA	5.0	137.35/137.77
SBA-1	22.5	1698
SBA-2	8.2	1702.5
SBA-3	13.1	1707
SLA	22.5	1544.5
VRA	9.0	137.5/137.62
SOA(1)	10.6	1702.5
SOA(2)	10.3	2247.5

- (1) Earth facing antennule. Assumed to be co-located with the earth-facing antennule of another S-Band omni. Normally only the beacon will radiate when the AMSU is on. For both omnис radiating assume each one produces the given field strength and omit SBA-2.
- (2) Earth-facing antennule of launch/emergency omni.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 90

3.4.3 Flight Environment

The AMSU-A2 shall survive the environment detailed in Section 3.7.3 of the General Instrument Interface Specification, IS-3267415. Exceptions or special precautions which must be taken during exposure to these environments are detailed below: AMSU-A2 shall meet the flight environment requirements as specified in GSFC S-480-40, Performance Assurance Requirements for the AMSU-A.

3.5 Operational Requirements and Precautions

3.5.1 Storage Requirements

- (1) General: The AMSU-A2 shall be stored in its transit case.
- (2) Temperature Limits: $75 \pm 10^{\circ}\text{F}$
- (3) Humidity Limits: Maximum Humidity 55%
- (4) Storage Pressure: The AMSU-A2 shall be stored in its transit case. GE shall provide dry nitrogen periodically as required in the instrument O&M manual.
- (5) Other: The AMSU-A2 shall be bench tested at least once every 9 months with the exception that it must have been tested within 6 months before being removed from storage for installation on the spacecraft.

3.5.2 Test Requirements

- (1) General: The AMSU-A2 instrument, being a total power radiometer, is extremely sensitive to the ambient test temperature and temperature changes. Without a controlled environment and test target, testing of the instrument is limited to an aliveness test. Variations in radiometer output response is normal when tested under uncontrolled conditions. This instrument is ESD sensitive.
- (2) Handling: Specified in AE-26357, AMSU-A1 & A2 Handling Procedure.
- (3) Temperature Limits:
Operating - Within Test Specification: -7 to +30°C
Operating - Survival: -20 to +58°C
Non-Operating (Not Powered): -15 to +50°C (Refer to Table 14)
- (4) Cleanliness: All spacecraft tests shall be performed in a Class 100,000 cleanroom environment except for acoustics, pyro shock, T-V preparations, and during transportation. For these tests the instrument vendor will provide protective covers or instructions how to bag them with a protective film.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 91

3.5.3 Operational Requirements

3.5.3.1 Command Sequences

Command sequences for AMSU-A2 operations shall be as follows:

NOTE: A minimum 18 second delay is required between subsequent AMSU-A2 commands.

Exception: No time delay between Module Off command and Survival Heater On commands.

3.5.3.1.1 Turn-On Sequence (In-Orbit and Test)

- 1) Send Survival Heater Power ON command (per spacecraft launch stored command table within 15 minutes of handover).
- 2) If RF Shelf temperature is $>-25^{\circ}\text{C}$, then proceed.
- 3) Send Survival Heater Power OFF command.
- 4) Send Module Totally OFF command to Not OFF (logic 0).
- 5) Send Module Power Connect command (S/Ns 101-109). Read L.O. temperatures (Digital A) (S/Ns 101-104 only)
- 6) Send Cold Cal Position MSB command to 0 (logic 0).
- 7) Send Cold Cal Position LSB command to 0 (logic 0).
- 8) Send Full Scan command to ON (logic 1).
- 9) Send Scanner A2 Power command to ON (logic 1)
- 10) Send Compensation Motor Power command to ON (logic 1).

NOTE: Steps 11-18 apply to S/Ns 101-104 only.

- 11) Delay 2 minutes.
- 12) If L.O. temperature at Module Power Connect (Step 5) is $<+5^{\circ}\text{C}$, wait until L.O. temperature is $\geq+5^{\circ}\text{C}$, then go to Step 14.
- 13) If L.O. temperatures at time of Module Power Connect (Step 5) $\geq+5^{\circ}\text{C}$, skip Steps 14-18 (turn-on is complete).
- 14) Send Module Totally OFF command to OFF (logic 1)
- 15) Delay 20 seconds.
- 16) Send Module Totally off command to Not OFF (logic 0).
- 17) Send Module Power Connect command.
- 18) Repeat Steps 5 through 10.

Note: Command 1 (Survival Heater ON) is not required for ambient turn-on.

3.5.3.1.2 Turn-Off Sequences

3.5.3.1.2.1 Normal Turn-Off Sequence (Instrument at zero power/predetermined instrument configuration).

- 1) Send Module Totally Off command to OFF (logic 1)

NOTE: This command puts the antenna in the warm cal position, turns off power to the scanner, and disconnects the +28 VDC main and pulse load busses.

- 2) Send Survival Heater Power OFF command

3.5.3.1.2.2 Emergency Off Sequence (Instrument at zero power/undetermined instrument configuration)

- 1) Send Module Disconnect command

NOTE: Instrument power OFF - unknown state.

3.5.3.1.3 Safestate Sequence (known spacecraft condition/instrument at minimum power/predetermined instrument configuration)

- 1) Send Module Totally OFF command to OFF (logic).
- 2) Send Survival Heater Power ON command.

3.5.3.1.4 Turn-On Sequence After Emergency OFF

- 1) Send Module Totally off command to OFF (logic 1)
- 2) Send Module Power Connect command
- 3) Delay 20 seconds
- 4) Perform turn-on per Section 3.5.3.1.1

3.5.3.2 Test Turn-On Constraints

- (1) Pressure: None
- (2) Radiation: GSFC X-600-87-11
- (3) Solar and Albedo: None
- (4) Magnetic Fields: None
- (5) Survival Heater Power must be OFF

3.5.3.3 Initial In Orbit Turn-On Constraints

- (1) See Table 14, Item 4
- (2) Survival Heater Power must be OFF

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 93

3.5.3.4 AIP Switchover

If the AIP switchover occurs and the redundant side starts up with a random phase 8 second sync with respect to the original sync, the AMSU-A2 will resync itself at the next 8 second sync pulse.

3.5.3.5 Launch Configuration

Instrument power off and the antenna in the warm cal (stow) position.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 94

4.0 INSTRUMENT INTEGRATION, TEST AND OPERATING REQUIREMENTS AND CONSTRAINTS

4.1 Test Equipment and Service

4.1.1 Equipment to be Supplied by Instrument Contractor to the Spacecraft Contractor

The following is an inventory of the equipment that shall be supplied by the instrument contractor:

- (a) Special Test Equipment (STE) - This unit shall be capable of operating the instrument in all its operating modes.
- (b) Contamination Covers - This cover(s) shall be used to minimize the accumulation of contamination on optical surfaces both during the bench check testing and while the instrument is on the spacecraft.
- (c) Handling Fixture - The handling fixture shall be attached to the AMSU-A2 at the time of shipment from the instrument contractor and shall remain attached to the instrument in its shipping container. It shall be used to lift the instrument from its shipping container and shall also be used to handle the instrument during bench operations. It shall be removed from the instrument prior to installation of the instrument on the spacecraft.
- (d) Thermal Blankets - The thermal blankets are shown on the detailed drawings, Aerojet 1333965. These blankets shall be shipped with each instrument.
- (e) Connector Savers - A set of connector savers shall be provided with each instrument. These connector savers shall remain on the instrument until it is integrated on the spacecraft and shall not be removed until after the IPF is performed.
- (f) Optical Alignment Equipment - A permanent alignment mirror shall be provided.
- (g) Thermal Vacuum Target and Controller - (The following is for both AMSU-A1 & A2) the thermal targets and monitoring equipment will consist of:

2-A1 Targets - Aerojet Dwg. No. 1333150-5&6

1-A2 Target - Aerojet Dwg. No. 1333202-3

The following items are contained in one console:

2-Mainframes - Azonix No. MFE1-64-S1-110-60
4-Expansion Chassis - Azonix No. EXCC-02-110
7-General Purpose I/O boards - Azonix No. GI05
13-Mother boards - Azonix No. AIB1
25-RTD Modules - Azonix No. RT44

- (h) Cables - The cables required to connect the STE to the instrument shall be supplied.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 95

- (i) **Lifting Fixture** - This fixture shall be attached to the instrument and shall allow the instrument to be mounted to the spacecraft when the spacecraft is in the vertical position. The fixture shall have provisions for lifting with a crane.

4.1.1.1 Special Test Equipment (STE)

The Special Test Equipment (STE) shall consist of:

a) Console Mod. Assy.	Aerojet Dwg. No. 1335696 and 1356655-1
b) Monitor and Keyboard	Tektronix Model 4208 or equivalent
c) Printer	Digital Model LA210 and LN14N-CA
d) Interconnect Cables	Aerojet Dwg. No.'s
W19 1335752	
W20 1335753	
W21 1335754	
W22 1335755	
W23 1335756	
W24 1335757	
W25 1335758	

4.1.1.2 Calibration Test Equipment (CTE)

Refer to Para. 4.1.1.g.

4.1.1.3 Contamination Cover

The contamination covers shall consist of an electrostatic cover and an EMI cover, Aerojet Dwg. No. 1333135.

4.1.1.4 Handling Fixture

The handling fixture shall be as shown in the Aerojet O&M Manual. The operation instructions for use of the fixture shall be given in the Aerojet O&M Manual.

4.1.1.5 Thermal Blankets

The thermal blankets shall be as detailed in Aerojet drawing no. 1333965(S/N 102-104) and No. 1360085 (S/N 105-109). Blankets shall be installed by the spacecraft contractor per spacecraft contractor procedure TP-BLKT 3278200 and Dwg. No. 8574806 (NOAA-L), 8574807 (NOAA-M) 8574808 (NOAA-N), 8574809 (NOAA-N').

The spacecraft contractor will determine the location of the velcro on the instrument blankets that mates to the spacecraft skirt blankets. The spacecraft contractor will attach this velcro to the instrument blankets per LMSSC drawing 8575175. The area where the velcro is attached will be covered by the spacecraft blankets.

4.1.1.6 Optical Alignment Equipment

The permanent alignment cube shall be as shown in Aerojet 1333965.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 96

4.1.1.7 Lifting Fixture

The lifting fixture shall be as shown on Aerojet Dwg No. 1333090 and drawing number T1291013-
1. The operating instructions for use of the fixture are given in the Aerojet spacecraft integration
for the AMSU-A system (AE-26157).

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 97

4.1.2 Services Provided by Instrument Contractor at the Spacecraft Contractor

4.1.2.1 Bench Test

The Incoming Inspection - Electrical Bench Test (4.3.1.4) of the first Flight Model (Proto Flight Instrument) shall be performed by instrument contractor personnel. During the performance of this test the instrument contractor will instruct the assisting spacecraft contractor personnel in the use of the STE and the performance of the bench test. Instrument contractor personnel shall be available for subsequent PFM Bench Test(s) and the Bench Test(s) of the Flight Instrument as directed by NASA.

4.1.2.2 Data Analysis

There are no provisions to send instrument contractor personnel to the spacecraft contractor to review data other than informally or in a trouble-shooting mode as directed by NASA. Instrument contractor personnel shall be present at the spacecraft contractor during initial integration of the Proto Flight Model. As directed by NASA, the instrument contractor personnel shall be present for selected system tests following integration of the Proto Flight Model and for integration and test of the Flight Instruments.

4.1.2.3 Troubleshooting

Instrument Contractor and GSFC personnel shall be available to assist in troubleshooting as directed by NASA.

4.1.2.4 Warranty

There are no warranty provisions between the instrument Contractor and the spacecraft contractor. If repair of an AMSU-A2 is necessary NASA will arrange with the instrument Contractor to have them completed.

If the AMSU-A2 must be shipped back to the vendor, the spacecraft contractor will assure the unit is packed in the original shipping container.

The spacecraft contractor will arrange all transportation, at the direction of NASA, and intermediate storage to conform to the storage environmental limits in this specification. If the instrument is to be shipped by air, the spacecraft contractor will escort the shipment to the air terminal.

The spacecraft contractor transportation office will make these arrangements based upon the local climate at the time of shipment. If for some reason these environmental limits cannot be assured, the shipment will be held, and NASA will be notified.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 98

4.1.2.5 Equipment Maintenance to be Supplied by Instrument Contractor

As directed by NASA, the instrument contractor shall be responsible for maintenance of all test equipment delivered to the spacecraft contractor until the end of the contract, except for any designated, commercial test instruments which will be maintained by the spacecraft contractor. The test equipment to be maintained by the instrument contractor shall include the STE/CTE and automated data system.

Maintenance or repairs can be done at the spacecraft contractor, or, in the event any equipment needs to be shipped to the instrument contractor, the spacecraft contractor will accept responsibility for all transportation arrangements as defined in Paragraph 4.1.2.4 of this document.

4.1.3 Software to be Supplied by the Instrument Contractor to the Spacecraft Contractor

4.1.3.1 Bench Test Procedure

The Bench Test Procedure shall be supplied to the spacecraft contractor concurrent with delivery of the STE. The preliminary versions of this procedure shall be submitted to the spacecraft contractor as generated.

4.1.3.2 GSE Operations Manuals and Procedures

The ancillary manuals and procedures necessary for use of the various test equipment shall be shipped to the spacecraft contractor concurrent with delivery of the STE; preliminary version of these documents shall be submitted as generated. The documents covered by this paragraph shall be in the Aerojet O&M Manual.

4.1.3.3 Data Book, Specification Verification and Calibration

A data book shall be supplied with each instrument. The alignment portion shall contain:

- (a) Instrument Alignment to its mounting surface;
- (b) Electrical boresights WRT optical alignment cube;
- (c) Size, Weight and Center of Gravity of each module.

The calibration data shall comprise:

- (a) Conversion equations for Digital A telemetry
- (b) Conversion Equations for Analog telemetry

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 99

4.1.3.4 Handling Procedures

The Instrument Handling Procedure, Aerojet O&M Manual, shall be delivered with the Proto Flight Model. Preliminary versions of this document shall be submitted to the spacecraft contractor as generated.

4.1.4 Equipment and Services to be Supplied by the Spacecraft Contractor for Direct Instrument Support

4.1.4.1 Spacecraft Contractor Supplied Equipment and Services

a. Power Input at Test Location

- (1) 115 Vac, 60 Hz, Single Phase, 20 Amp. Service for STE
- (2) 115 Vac, 60 Hz, Single Phase, 25 Amp. Service for CTE

b. Floor Space to Accommodate the Following Equipment:

		Size (Inches)	Weight (Pounds)
1)	STE Printer	33 x 21.5 23 x 16	400 25
2)	CTE A2 Target	16.5 x 12.5	116 (1 required)

c. CTE Target:

LN₂ at 20 lb/hr flow rate and supply pressure approximately 5 psi shall be provided by the spacecraft contractor for spacecraft level thermal vacuum. The thermal vacuum chamber cabling for the CTE shall be supplied by the spacecraft contractor.

d. Test Area

The spacecraft contractor shall provide a test area for the AMSU-A2 which meets the following environmental requirements:

- 1. Cleanliness: Class 100,000
- 2. Temperature Limits: 65°-85°F (18 - 29°C)
- 3. Relative Humidity: 55 Percent Max.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 100

e. Standard Test Equipment

The standard test equipment shall be available at the spacecraft contractor to set up and troubleshoot the STE/CTE and to use during the bench test and post storage tests.

4.1.4.2 Spacecraft Contractor Supplied Labor for Testing at the Instrument Level

- a. First Flight Model: - The spacecraft contractor shall assist the instrument contractor personnel in performing the Bench Test.
- b. Flight Models and Post Storage Testing: - The spacecraft contractor shall perform the Bench Tests. The bench test shall be performed at nine (9) month intervals on instruments not mounted on a spacecraft.

4.1.5 Test Access to the AMSU-A2

4.1.5.1 During Bench Checkout

All electrical interfaces to the instrument shall be through the AMSU-A2/Spacecraft connectors. There are test connectors on the AMSU-A2 but these are to be used only during the Bench Checkout; access to them will not normally be required.

4.1.5.2 During Satellite Level Tests

Access will be required to the instrument during the spacecraft level testing to remove the protective cover over the antennae. The cover will be kept on the scan cavity during all testing except the (1) RFI test, (2) vibration and (3) during the thermal vacuum test. During these tests precautions shall be taken to prevent dust and any other foreign material from entering the scan port.

4.1.5.3 Access for Inspecting Scan Antennae, Reflectors, and Thermal Mirrors

Access to the instrument will be required just before enclosing the spacecraft with the shroud for the purpose of removing the protective covers on the antennae, inspecting the antennae and reflectors and for inspecting and cleaning the Thermal Mirrors at WTR.

4.1.5.4 During Launch Pad Testing (Shroud On)

There shall be no need for visual inspection of the instrument on the Launch pad. There will be no targets mounted in the fairing for the instrument use.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 101

4.2 Acceptance Test Performed at the Instrument Vendors

The tests that are to be performed by the Instrument Vendors shall be as defined in the GSFC Specification for the ADVANCED MICROWAVE SOUNDING UNIT, Document No. GSFC-S-480-13.

4.3 Testing at the Spacecraft Contractor's Facility

The objective of testing the instrument at the spacecraft contractor's facility is to assure compatibility of the instrument with the spacecraft and to demonstrate that the instrument meets its specified characteristics. The test program is divided into tests performed on the instrument only, i.e., the Instrument Evaluation Tests; and on the instrument as part of the spacecraft system, i.e., the System Evaluation Tests and the Environmental Tests. The test flow is given in Figure 15. Test failures related to the instrument will be documented by a Test Discrepancy Report per the spacecraft contractor operating instruction PAP E8.3 as specified in the Quality Assurance Plan, 3267412.

4.3.1 Instrument Evaluation Tests

The objective of the Instrument Evaluation Tests is to demonstrate that the instrument has the same characteristics at the spacecraft contractor as it did when tested at the instrument contractor's plant before shipment. At the completion of the Evaluation Tests the instrument is either put on the spacecraft or is put into storage to wait for later mounting. This evaluation test is divided into Receiving, Incoming Inspection Mechanical, and Incoming Inspection Electrical. Storage and storage retesting are also considered part of the Instrument Evaluation Tests.

4.3.1.1 Receiving

The objective of the receiving tests and inspection is to detect any gross damage during shipping and to verify delivery of documentation supplied with the instrument. The transit package shall not be opened during receiving inspection. Alignment and calibration and other instrument related data will be reviewed by the spacecraft contractor's Systems Engineering.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 102

4.3.1.2 Incoming Inspection - Mechanical

The objective of the mechanical incoming inspection is to check for physical damage to the instrument and to document its condition as received at the spacecraft contractor. The state of the shock indicators shall be determined and the state shall be recorded. The instrument shall be weighed. This weight shall be used in establishing the full spacecraft weight. The mechanical inspection which requires the removal of the scan cavity dust cover shall be done in an environment which meets the Class 100,000 requirements.

4.3.1.3 Degaussing

The AMSU-A2 shall not be degaussed.

4.3.1.4 Incoming Inspection - Electrical (Bench Test)

The Bench Test shall be performed to ensure that the electrical and functional characteristics have not changed as a result of shipping. The STE shall be separately tested before being connected to an instrument.

4.3.1.5 Storage and Storage Testing

The AMSU-A2 shall be stored following the Incoming Electrical Inspection if not integrated on a waiting spacecraft.

The purpose of Storage testing is to assure that the instrument has not failed during storage. Instruments in storage shall be tested nine (9) months after the last bench test and every nine months thereafter. These periodic tests shall be comprised of a Bench Test.

Instruments which have been in storage more than six (6) months shall undergo a Bench Test before installation on the spacecraft. The requirements are given in Paragraph 3.5.1 of this specification.

4.3.1.6 Instrument Test Matrix

The instrument level and spacecraft level test matrix is given in Tables 16A and 16B.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 103

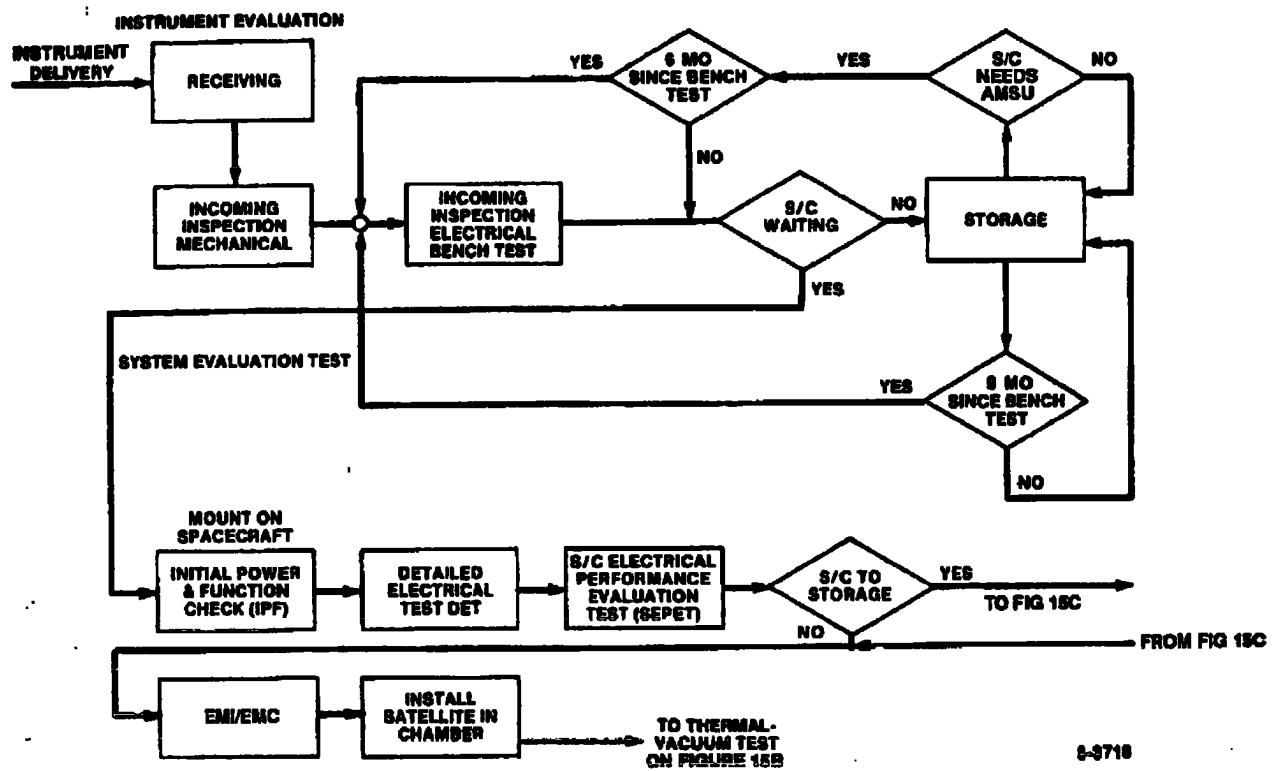


Figure 15A. AMSU-A2 Testing at the Spacecraft Contractor's Facility

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
Sheet 104		

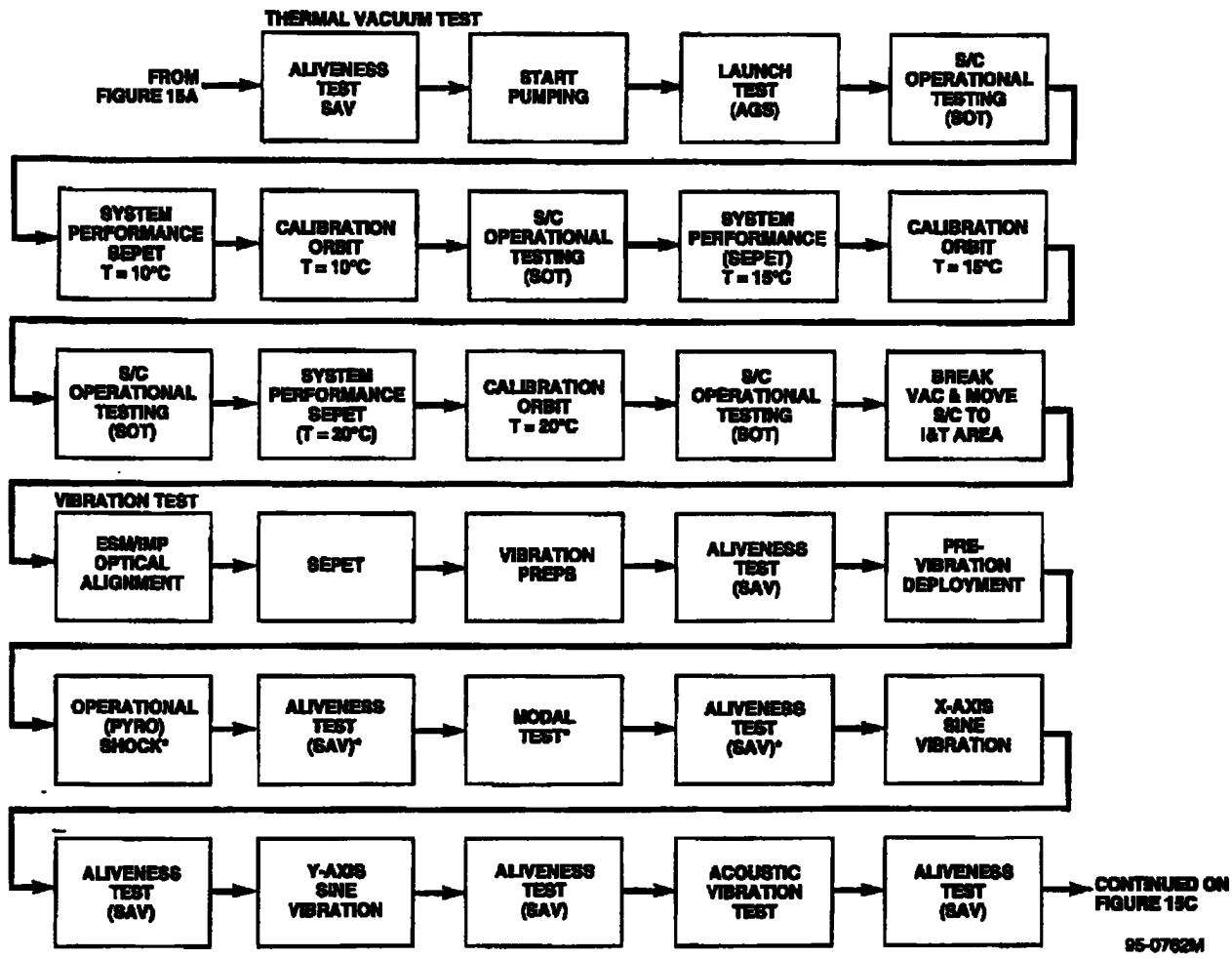


Figure 15B. AMSU-A2 Testing at the Spacecraft Contractor's Facility

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 105

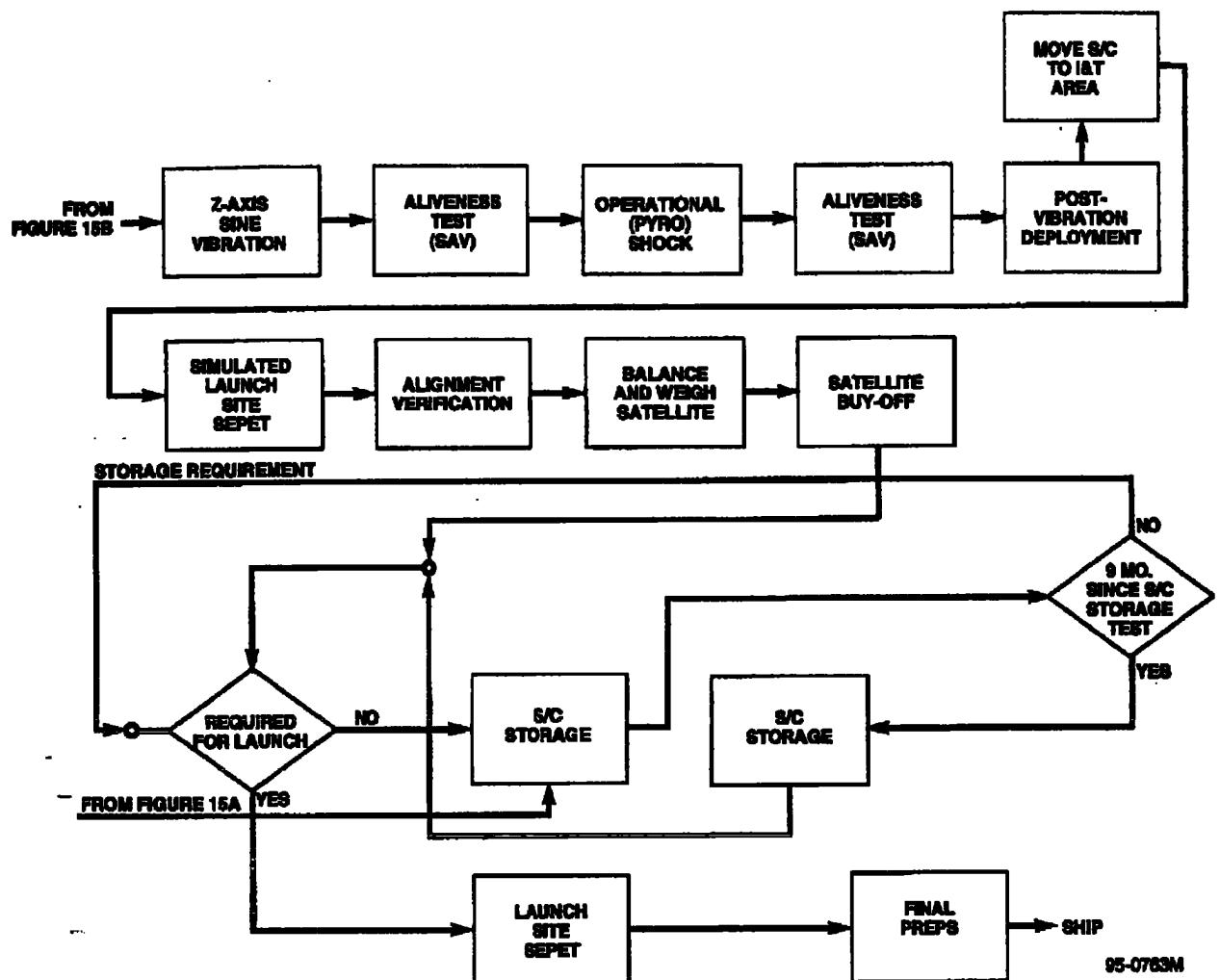


Figure 15C. AMSU-A2 Testing at the Spacecraft Contractor's Facility

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 106

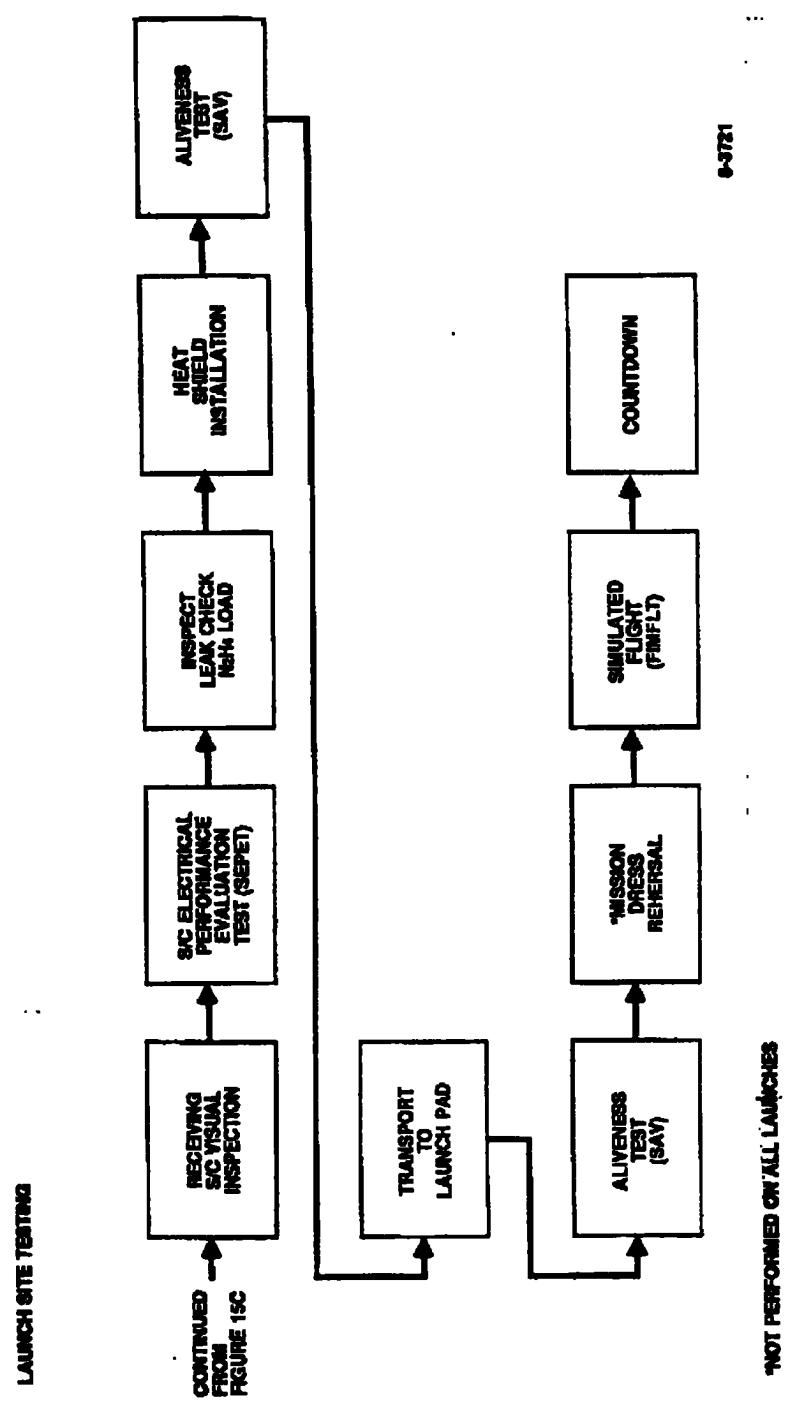


Figure 15D. AMSU-A2 Testing at WTR

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 107

TABLE 16A. AMSU-A2 TEST MATRIX

TEST	BENCH TEST	SYSTEM EVALUATION				THERMAL VACUME		
		IPF	DET	SEPET	ALIVE-NESS	AGS	SEPET	CAL CHECK
REFERENCE PARAGRAPH	4.3.1.4	4.3.3.1	4.3.3.2	4.3.3.3	4.3.4.1	4.3.4.2		
POWER STATUS S/C PWR OFF	X							
S/C ON, AMSU-A2 OFF	X	X	X	X	X	X	X	X
AMSU-A2 ON	X	X	X	X	X		X	X
1. Ground Resistance Measurements		X						
2. Harness Verification		X						
3. Power Measurements	X	X						
4. Input Signal Level Measurement	X							
5. Command / Mode Verification	X		X	X	X		X	X
6. Output Signal Level Measurement	X		X					
7. Digital "A" TM Format Verification	X		X	X	X		X	X
8. Limit Check Digital "A" TM	X		X	X	X		X	X
9. Limit Check Analog Telemetry	X	X	X	X	X	X	X	X

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483	
		Sheet 108	

TABLE 16B. AMSU-A2 TEST MATRIX

TEST	ENVIRONMENTAL TESTS				FINAL SEPET
	<u>OPTICAL ALIGNMENT</u>	<u>SINE VIBRATION</u>	<u>ACOUSTIC VIBRATION</u>	<u>POST-VIB DEPLOYMENT</u>	
REFERENCE PARAGRAPH	<u>4.3.4.3</u>	<u>4.3.4.4</u>	<u>4.3.4.5</u>	<u>4.3.4.6</u>	<u>4.3.4.7</u>
POWER STATUS S/C PWR OFF	X				
S/C ON, AMSU-A2 OFF	X	X	X	X	X
AMSU-A2 ON					
1. Ground Resistance Measurements					
2. Harness Verification					
3. Power Measurements					
4. Input Signal Level Measurement					
5. Command/Mode Verification					X
6. Output Signal Level Measurement					
7. Digital "A" TM Format Verification					X
8. Limit Check Digital "A" TM					X
9. Limit Check Analog Telemetry	X	X	X		X

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 109

4.3.2 Mounting to Spacecraft

When the AMSU-A1 module is to be mounted on the spacecraft, it will be placed on a clean bench and the handling fixtures will be removed. The lifting fixture, after having been cleaned, will be attached to the module. The scan cavity dust covers will be checked for proper installation. The AMSU-A2 module will then be installed on the spacecraft.

4.3.3 System Evaluation Test

The objectives of the System Evaluation Test are to integrate the instrument to the spacecraft system and to assure that the AMSU-A2 meets all interface requirements.

The System Evaluation Test is divided into the Initial Power and Functional Check (IPF); the Detailed Electrical Test (DET); and the Spacecraft Electrical Performance Evaluation Test (SEPET).

For all tests the instrument is mounted on the spacecraft and the test data can be processed by the ATNAGE.

4.3.3.1 Initial Power and Functional Checks (IPF)

The objectives of the Initial Power and Functional Checks are (1) to provide an orderly method of verifying that application of power to the AMSU-A2 will not damage it or previously integrated subsystems; and (2) to verify that, after mating the correct electrical interface has been established.

Correct operation of the instrument will be established by the use of breakout boxes and probes as required. Input signal voltages and power level measurements will be made on the spacecraft harness prior to mating with the AMSU-A2. Breakout boxes and/or probes may be used to expedite the measurement of signal levels and loading in all operational modes. However, the use of any breakout box or probe at the AMSU-A2/spaceship interface will be subject to the following provisions: (1) all voltage taps will be protected against damage by external shorts pin-to-pin and pin-to-ground and no breakout box will contain more than one AMSU-A2 connector; and (2) all power level or current measurements will be made using clip-on induction probes and extender harnessing. The parameters to be tested during the IPF will be the following:

- (a) Case Grounding - Verify case ground is firmly attached to the spacecraft ground.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 110

- (b) **Harness verification** - These measurements verify that electrical inputs to the instrument are on the correct pins. The presence of power on input pins, both full time and switched, is verified. Command functions on assigned lines are verified. Clock signals on assigned lines are verified. This harness verification is done prior to initial instrument installation. If the AMSU-A2 is exchanged the harness verification will not be repeated. Resistance of all AMSU-A2 S/C Harness ground return lines will be measured.
- (c) **Instrument ground isolation** - All power supply and signal grounds will be checked for isolation from the spacecraft ground before the spacecraft harness is connected.

4.3.3.2 Detail Electrical Test (DET)

The purpose of the Detailed Electrical Test is to demonstrate that the correct interface exists between the instrument and the spacecraft. The DET will include a functional checkout in which the instrument is commanded into each of its states to verify correct electrical and mechanical response. The Primary Contamination cover will be in place during DET testing. The parameters to be tested during the DET will be:

- (a) **Input Signal Level Measurement** - The measurements of the clock signal and command signal levels are made to ensure that the instrument is supplied the correct amplitude signal and that the input of the instrument does not load down the driving circuit.
- (b) **Command/Mode Verification** - Verification of the correct response to each command will be measured by the mechanical response and electrical output. Status verification will also be performed using Digital A Status Monitors and Digital B telemetry.
- (c) **Output Signal Level Measurements (Except for Radiometric Data)** - The measurement of the output signal levels will be made to ensure that the instrument is supplying the correct levels to the spacecraft and the spacecraft does not incorrectly load the circuits. The measurement will also verify that signals exist at each of the outputs of the Digital B Telemetry and Analog Telemetry which corresponds to the operating function.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 111

- (d) Scan Operation Verification - The correct scan operation will be verified using the information output contained in the Digital A data stream.
- (e) Digital A Data Format Verification - Verification of the Scientific Data Format will be demonstrated by the ability of the ATNAGE to decode and display all of the AMSU-A2 words contained in the Digital A data stream. In addition this test will validate the data base being used with the instrument.
- (f) Analog Telemetry Verification - Verification of the operation of each of the Analog Telemetry points will be demonstrated by ATNAGE limit checking. This test will also verify the validity of the data base for the specific serial numbered instrument.

4.3.3.3 Spacecraft Electrical Performance Evaluation Test (SEPET)

The test has two basic objectives: (1) to demonstrate by measurement that the system meets all specification criteria; (2) to compare the data with previous measurements or establish the basis for future comparison. The SEPET is the most comprehensive ambient electrical test of the entire spacecraft.

The SEPET will be performed in a room temperature environment at atmospheric pressure.

- (a) Command/Mode Verification - Verification of correct response to each command will be measured by the mechanical response and electrical output. Status verification will also be performed using telemetry.
- (b) Limit Check - A number of Digital A telemetry words will be continuously limit checked in real time.
- (c) Limit Check Analog Telemetry - All analog telemetry will be limit checked.
- (d) Scan Verification - This test will verify the correct operation of the scan motor.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483

4.3.4 Satellite Environment Test

4.3.4.1 Aliveness Test

The aliveness test verifies that the instrument is correctly set up to enter a specific environment or has successfully passed the environmental exposure. The evaluation is accomplished by commanding the instrument through its orbital modes and status checking the data.

4.3.4.2 Thermal-Vacuum Tests

The purpose of the Thermal-Vacuum Test is to demonstrate the successful performance of the integrated satellite at temperature extremes in a vacuum environment.

The test will be performed with the spacecraft in the vacuum chamber at the spacecraft contractor's facility. The pressure will be less than 10^{-5} TORR and the walls of the chamber maintained at -65°C.

During the Thermal-Vacuum operation, the tests will be divided into AGS (launch simulation), Aliveness, System Performance, and Calibration check orbits. The functions to be tested in each of these tests are shown in Table 16. Details of the tests are given below:

- (a) AGS - A simulated launch test will be performed following pumpdown. The AMSU-A2 will be in its Launch mode.
- (b) T-V SEPET - The test has similar objectives to the SEPET performed in the ambient condition.
- (c) Calibration Check Orbits - The AMSU-A2 will be in a normal test mode. No special testing will be performed during the calibration orbits.
- (d) Transition Test - There will be no instrument testing during the time spacecraft temperatures are adjusted from one plateau to the next. However, the normal status monitoring and data processing will be done during the period of temperature transition.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 113

4.3.4.3 Optical Alignment

The purpose of this test is to determine the field-of-view of the instrument with respect to the satellite primary reference, the Earth Sensor Assembly (ESA). The measurement made during this test will be to determine the differences in pointing direction of the surfaces of an optical reference on the instrument and the axes defined by the AMSU-A1 optical axes. The instrument will be mounted so as to meet the placement requirement of ± 0.05 degrees relative to the AMSU-A1. This measured difference will be added to vendor supplied data which references the fields-of-view and axis to the instrument mounted cube coordinates.

4.3.4.4 Sine Vibration in X, Y, and Z Axes

The purpose of the sine vibration is to demonstrate the adequacy of the integrated spacecraft structure design. A low level (1/4 g or less) sine sweep will be conducted prior to the full level test.

Results will be used to verify the major critical resonances and adequacy of the individual components to withstand vibration in each of three orthogonal axes. The levels that the AMSU-A2 will see during this test will be monitored to ensure that they do not exceed the levels to which the instrument was qualified (Ref: GSFC-S-480-40, Revision P). The spacecraft will be vibrated in an all up flight configuration.

The AMSU-A2 module will be in its launch configuration. Some limited analog telemetry will be on during vibration. The scan cavity dust covers will be removed for this test. Between each axis of vibration the instrument will be inspected and an Aliveness Test will be performed (See Figure 15).

4.3.4.5 Acoustic Vibration

The purpose of the acoustic vibration test will be to demonstrate that acoustically generated noise levels more severe than those expected during launch, will not adversely affect or damage the spacecraft structure or the payload instruments.

4.3.4.6 Post-Vibration Deployment Test

The instrument will be subjected to vibration as the result of deployment of some satellite equipment. The deployment tests have four (4) parts: (1) boom deployment, (2) cant deployment, (3) solar array deployment, and (4) antenna deployment.

The instrument will be in the Launch mode for these tests.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 114

4.3.4.7 Final Electrical Check

The final electrical check will be a "Launch Site SEPET". This will be identical to the ambient SEPET.

5.0 NOTES

5.1 Waivers

The following waivers to the General Instrument Interface Specification (IS-3267415) have been granted for the AMSU-A2.

<u>Waiver</u>	<u>Date of Approval</u>
W15	A2 Structural Resonance below 100 Hz for S/N 101-104

Electromagnetic Interference (EMI)/
Conducted Emission (CCR 1438-Rev-A)
Exception: Conducted emission limits will
be as per figure 16 for AMSU-A2 S/N105
to 109.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 115

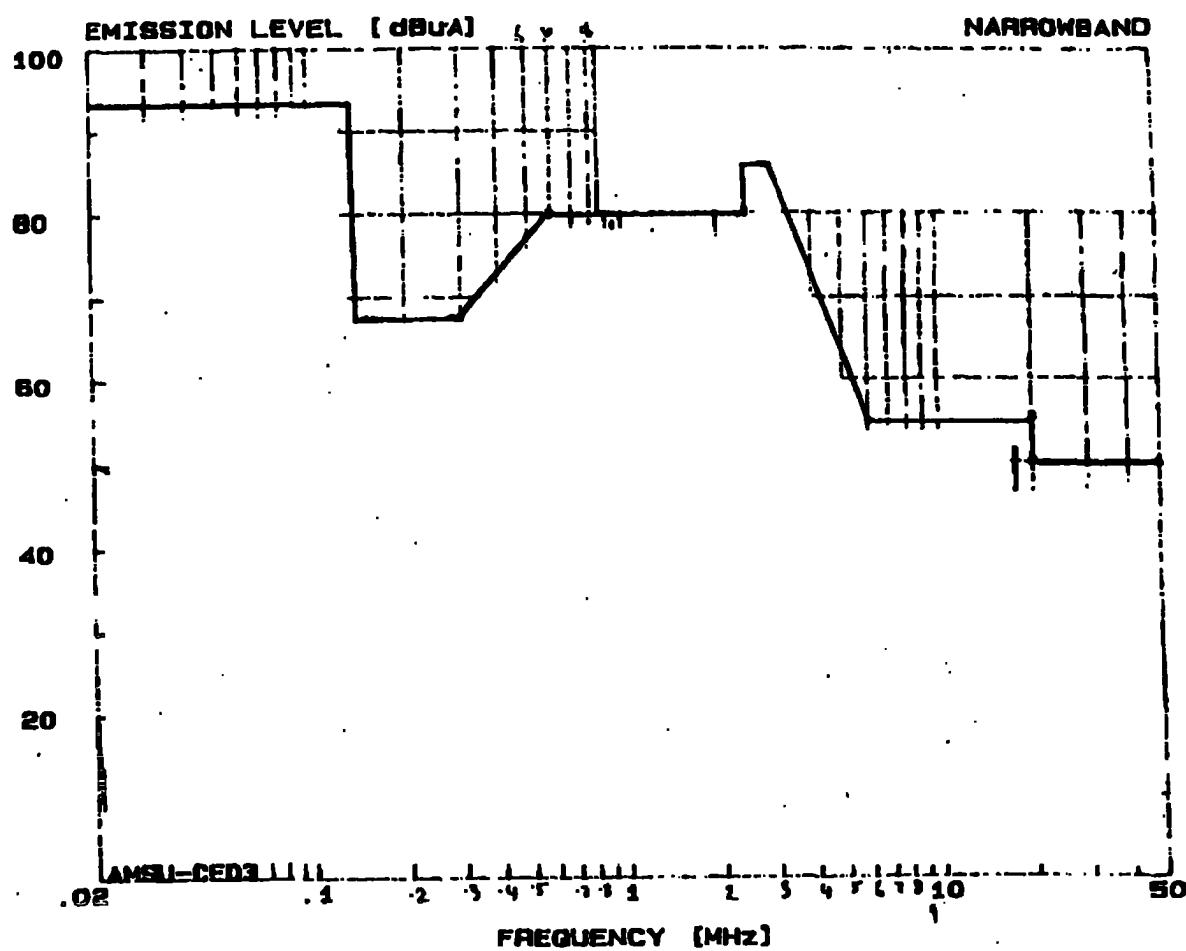


Figure 16. AMSU-A2 Conducted Emissions Limits (S/N105 to 109)

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483

APPENDIX A

REQUIREMENT DATES FOR AMSU-A2 INSTRUMENT DATA

		SCR	PDR	CDR
2.1.2	Instrument Contractor Originated Documents Thermal Interface Control Drawing Outline Interface Control Drawing (Mechanical) Electrical Interface Control Drawing		X	
	Top Assembly Drawing	X		X
	Bench Check Test Procedure Delivery of Inst.			
	Bench Check Unit Operation Delivery of BCU			X
	Instrument Handling Procedure			
	Spec Verification and Calib.	Delivery of Inst		
	Data Book			
	Reduced Thermal Model			X
3.1.2.4	Connector Keying Requirements		X	
3.1.3.2.1	Power Dissipation (Table 4)		X (+6 mos.)	
3.1.3.2.3	Load Current Ripple (Fig. 2)			X (+2 mos.)
3.1.3.2.4	Transient Loads (Fig. 4)			X (+2 mos.)
3.1.3.2.5	DC/DC Converter Frequency		X	
3.1.3.4.1	Power Dissipation			X
3.1.3.4.3	Transient Loads (Fig. 7)			X
3.1.3.5.1	Power Dissipation		X (+6 mos.)	
3.1.3.5.3	Transient Loads (Fig. 8)			X (+2 mos.)
3.1.4.2	Synchronization Signals	X		
3.1.4.3	Commands (Table 7)	X		
3.1.5.2.1	General Requirements		X	

NOTE: Where two X's appear for any item, the first X is the date by which preliminary data is required.

ITAR CONTROLLED DATA

Size	Code Ident No.			
A	06887	IS-2624483		
		Sheet 117		

APPENDIX A (Continued)

REQUIREMENT DATES FOR AMSU-A2 INSTRUMENT DATA

		SCR	PDR	CDR
3.1.5.3.2	Digital "B" Telemetry Points (Table 10)		X	
3.1.5.4.2	Analog Telemetry Points (Table 11)		X	
3.1.6	Operations		X	
3.1.6.1	Input Test Points		X	
3.1.6.2	Output Test Points		X	
3.2.1.1	Dimensions		X	
3.2.1.3	Moments of Inertia		X	
3.2.1.5	Center of Gravity		X	
3.2.2.1	Instrument Mounting Surface	X		
3.2.2.2	Mounting Hole Position			
3.2.5.1	Reference Surfaces		X	
3.2.6.1	Accessibility			X
3.2.6.2	Installation Requirements			X
3.2.6.4	Precautions			X
3.2.7	Inst. Material and Finishes		X	
3.2.8	Spacecraft Harness Clamp Requirements		X	
3.3.3	Temperature Design Limits		X	
3.3.4.1	Finishes		X	
3.3.4.2	Insulation Blankets		X	

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
		Sheet 118

APPENDIX A (Continued)

REQUIREMENT DATES FOR AMSU-A2 INSTRUMENT DATA

		SCR	PDR	CDR
3.4.1	Magnetic Characteristics		X	
3.4.3	Flight Environment		X	
3.5.1	Storage Requirements (Temp.)			X
3.5.2	Test Requirements			X
3.5.3.1	Command Sequences		X	
3.5.3.2	Turn-On Constraints			X
3.5.3.3	Initial Turn-On Constraints			X
4.0	Instrument Integration, Test and Operating Requirements & Constraints			X
5.1	Waivers*			

* As necessary

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483	
			Sheet 119

APPENDIX B ATNAGE SUBROUTINES FOR PROCESSING AMSU-A2 DATA

A. REAL TIME PROCESSING

Many of these functions require the instrument unique Software to be ON. Functions not requiring unique software are marked (*).

1. Raw Data Prints and formatted (Galoppo) prints.
2. Status Checking:
 - a. Prints out a status report on commands
 - b. Prints out when there is a "SCIENTIFIC DATA" status bit change. (Operator may inhibit from the keyboard).
3. Scan Verification: The correct position of each antenna in every scan mode is calculated. Errors are indicated when actual scan position does not agree with the expected position. The scan sync is also checked.
4. Limit Checker: The Limit check verifies that telemetry functions are within specified bounds. These bounds are established by data base and may be temporarily changed from the keyboard.
 - *a. Analog Telemetry functions
 - b. Digital A Housekeeping Telemetry functions
5. Radiance Monitor: Limit checks the warm and cold load radiometric channel data against high/low limits. Calculates scene temperature for two radiometric channels and limit checks the differences between these values and the temperature of the cold load and warm load target temperatures. Also limit checks the noise equivalent temperature difference levels of the two channels.
6. *Command Verification: Telemetry status bits which are expected to change when commands are sent are verified by corresponders. The telemetry status to be verified is defined in a data base.

ITAR CONTROLLED DATA

Size A	Code Ident No. 06887	IS-2624483
Sheet 120		